

Made by

Muhammad Usama and DUA sister

CS502 - Fundamentals of Algorithms

Quiz No.1 12-11-2012

Question # 1 of 10 (Start time: 06:18:58 PM) Total Marks: 1

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Question # 2 of 10 (Start time: 06:19:38 PM) Total Marks: 1

Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,

Select correct option:

left-complete

right-complete

tree nodes

tree leaves

Question # 3 of 10 (Start time: 06:20:18 PM) Total Marks: 1

Sieve Technique can be applied to selection problem?

Select correct option:

True

False

Question # 4 of 10 (Start time: 06:21:10 PM) Total Marks: 1

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

$(\log n)$ order

Question # 5 of 10 (Start time: 06:21:39 PM) Total Marks: 1

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A (an) _____ is a left-complete binary tree that conforms to the heap order
Select correct option:

heap

binary tree

binary search tree

array

Question # 6 of 10 (Start time: 06:22:04 PM) Total Marks: 1

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

Question # 7 of 10 (Start time: 06:22:40 PM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

Question # 8 of 10 (Start time: 06:23:26 PM) Total Marks: 1

The recurrence relation of Tower of Hanoi is given below $T(n) = \begin{cases} 1 & \text{if } n=1 \\ 2T(n-1) & \text{if } n > 1 \end{cases}$ In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option:

16

10

32

31

Question # 9 of 10 (Start time: 06:24:44 PM) Total Marks: 1

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

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Question # 10 of 10 (Start time: 06:25:43 PM) Total Marks: 1

For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

algebraic

logarithmic

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Slow sorting algorithms run in,

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

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In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

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$T(n)$

$T(n/2)$

$\log n$

$n/2 + n/4$

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

1

few

In which order we can sort?

Select correct option:

increasing order only

decreasing order only

increasing order or decreasing order

both at the same time

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10

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Analysis of Selection algorithm ends up with,

Select correct option:

$T(n)$

$T(1/1 + n)$

$T(n/2)$

$T((n/2) + n)$

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Divide-and-conquer as breaking the problem into a small number of
Select correct option:

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The analysis of Selection algorithm shows the total running time is indeed _____ in n ,
Select correct option:

arithmetic

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How many elements do we eliminate in each time for the Analysis of Selection algorithm?
Select correct option:

$n / 2$ elements

$(n / 2) + n$ elements

$n / 4$ elements

$2n$ elements

Sieve Technique can be applied to selection problem?

Select correct option:

True

false

For the heap sort we store the tree nodes in

Select correct option:

level-order traversal

in-order traversal

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pre-order traversal

post-order traversal

One of the clever aspects of heaps is that they can be stored in arrays without using any

_____.

Select correct option:

pointers

constants

variables

functions

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

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binary search tree

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Select correct option:

n / 2 elements

(n / 2) + n elements

n / 4 elements

2 n elements

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

Question # 1 of 10 (Start time: 08:17:23 AM) Total M a r k s : 1

The number of nodes in a complete binary tree of height h is

Select correct option:

$2^{(h+1)} - 1$

$2 * (h+1) - 1$

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$2 * (h+1)$

$((h+1) ^ 2) - 1$

Question # 2 of 10 (Start time: 08:18:46 AM) Total M a r k s: 1

A (an) _____ is a left-complete binary tree that conforms to the heap order

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In Sieve Technique we do not know which item is of interest

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False

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$T(n)$

$T(n / 2)$

$\log n$

$n / 2 + n / 4$

Question # 6 of 10 (Start time: 08:23:01 AM) Total M a r k s: 1

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

Theta asymptotic notation for $T(n)$:

Select correct option:

Set of functions described by: $c_1g(n) \geq f(n)$ for c_1 s

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Theta for $T(n)$ is actually upper and worst case comp

Set of functions described by:

$c_1g(n)$

Question # 8 of 10 (Start time: 08:24:39 AM) Total M a r k s: 1

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

1

few

Question # 9 of 10 (Start time: 08:25:54 AM) Total M a r k s: 1

Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

Question # 10 of 10 (Start time: 08:26:44 AM) Total M a r k s: 1

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Memorization is?

To store previous results for future use

To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later

To make the process accurate

None of the above

Question # 2 of 10 Total M a r k s: 1

Which sorting algorithm is faster

$O(n \log n)$

$O(n^2)$

$O(n+k)$

$O(n^3)$

Quick sort is

Stable & in place

Not stable but in place

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Stable but not in place

Some time stable & some times in place

One example of in place but not stable algorithm is

Merger Sort

Quick Sort

Continuation Sort

Bubble Sort

In Quick Sort Constants hidden in $T(n \log n)$ are

Large

Medium

Small

Not Known

Continuation sort is suitable to sort the elements in range 1 to k

K is Large

K is not known

K may be small or large

K is small

In stable sorting algorithm.

If duplicate elements remain in the same relative position after sorting

One array is used

More than one arrays are required

Duplicating elements not handled

Which may be a stable sort?

Merger

Insertion

Both above

None of the above

An in place sorting algorithm is one that uses ___ arrays for storage

Two dimensional arrays

More than one array

No Additional Array

None of the above

Continuing sort has time complexity of ?

$O(n)$

$O(n+k)$

$O(n \log n)$

$O(k)$

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We do sorting to,
keep elements in random positions
keep the algorithm run in linear order
keep the algorithm run in $(\log n)$ order
keep elements in increasing or decreasing order

In Sieve Technique we donot know which item is of interest

True

False

A (an) _____ is a left-complete binary tree that conforms to the heap order

heap

binary tree

binary search tree

array

27. The sieve technique works in _____ as follows

phases

numbers

integers

routines

For the sieve technique we solve the problem,

recursively

mathematically

precisely

accurately

29. For the heap sort, access to nodes involves simple _____ operations.

arithmetic

binary

algebraic

logarithmic

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

arithmetic

geometric

linear

orthogonal

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For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

algebraic

logarithmic

Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

Question # 9 of 10 (Start time: 07:45:36 AM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

For the heap sort we store the tree nodes in

Select correct option:

level-order traversal

in-order traversal

pre-order traversal

post-order traversal

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

upper

lower

average

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log n

single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

(log n) order

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

T(n)

T(n / 2)

log n

n / 2 + n / 4

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

For the Sieve Technique we take time

Select correct option:

T(nk)

T(n / 3)

n²

n/3

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In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

linear

arithmetic

geometric

exponent

Analysis of Selection algorithm ends up with,

Select correct option:

$T(n)$

$T(1 / 1 + n)$

$T(n / 2)$

$T((n / 2) + n)$

Quiz Start Time: 07:23 PM

Time Left 90

sec(s)

Question # 1 of 10 (Start time: 07:24:03 PM) Total M a r k s: 1

In in-place sorting algorithm is one that uses arrays for storage :

Select correct option:

An additional array

No additional array

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

Time Left 89

sec(s)

Question # 2 of 10 (Start time: 07:25:20 PM) Total M a r k s: 1

Which sorting algorithm is faster :

Select correct option:

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

In stable sorting algorithm:

Select correct option:

One array is used

In which duplicating elements are not handled.

More than one arrays are required.

Duplicating elements remain in same relative position after sorting.

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Counting sort has time complexity:

Select correct option:

$O(n)$

$O(n+k)$

$O(k)$

$O(n \log n)$

Counting sort is suitable to sort the elements in range 1 to k:

Select correct option:

K is large

K is small

K may be large or small

None

Memorization is :

Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of recursive calls and looking them again if needed later

To make the process accurate.

None of the above

The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

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Not known

small

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Stable and not in place

Some time in place and send some time stable

For the Sieve Technique we take time

T(nk)

T(n / 3)

n²

n/3

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

Many

1

Few

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

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2-dimension Maxima

Which may be stable sort:

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Both of above

Selection sort

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

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arithmetic

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In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large
Medium
Not known
small

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$
T(n)
 $T(\log n)$
 $T(n \log n)$

Counting sort has time complexity:

Select correct option:

$O(n)$
 $O(n+k)$
 $O(k)$
 $O(n \log n)$

In which order we can sort?

Select correct option:

increasing order only
decreasing order only
increasing order or decreasing order
both at the same time

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap
binary tree

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binary search tree

array

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

Select correct option:

arithmetic

geometric

linear

orthogonal

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

Select correct option:

There is explicit combine process as well to conquer the solution.

No work is needed to combine the sub-arrays, the array is already sorted

Merging the sub arrays

None of above.

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

upper

lower

average

$\log n$

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

$T(n)$

$T(n / 2)$

$\log n$

$n / 2 + n / 4$

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None of above

The number of nodes in a complete binary tree of height h is

$$2^{(h+1)} - 1$$

$$2 * (h+1) - 1$$

$$2 * (h+1)$$

$$((h+1) ^ 2) - 1$$

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

$n / 2$ elements

$(n / 2) + n$ elements

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$2 n$ elements

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

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We do sorting to,

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Slow sorting algorithms run in,

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$T(\log n)$

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One of the clever aspects of heaps is that they can be stored in arrays without using any

Pointers

Constants

Variables

Functions

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K is large

K is small

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K may be large or small

None

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Question # 2 of 10 (Start time: 06:19:38 PM) Total Marks: 1

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- arithmetic
- geometric
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- orthogonal

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Sieve Technique can be applied to selection problem?
Select correct option:

- True
- false

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Select correct option:

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- post-order traversal

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$n/2 + n/4$

Question # 6 of 10 (Start time: 08:23:01 AM) Total M a r k s: 1

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

Theta asymptotic notation for $T(n)$:

Select correct option:

Set of functions described by: $c_1g(n)$ Set of functions described by $c_1g(n) \geq f(n)$ for c_1 s

Theta for $T(n)$ is actually upper and worst case comp

Set of functions described by:

$c_1g(n)$

Question # 8 of 10 (Start time: 08:24:39 AM) Total M a r k s: 1

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

Made by

Muhammad Usama and DUA sister

1

few

Question # 9 of 10 (Start time: 08:25:54 AM) Total M a r k s: 1

Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

Question # 10 of 10 (Start time: 08:26:44 AM) Total M a r k s: 1

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Memorization is?

To store previous results for future use

To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later

To make the process accurate

None of the above

Question # 2 of 10 Total M a r k s: 1

Which sorting algorithm is faster

$O(n \log n)$

$O(n^2)$

$O(n+k)$

$O(n^3)$

Quick sort is

Stable & in place

Not stable but in place

Stable but not in place

Some time stable & some times in place

One example of in place but not stable algorithm is

Merger Sort

Quick Sort

Continuation Sort

Bubble Sort

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In Quick Sort Constants hidden in $T(n \log n)$ are

Large

Medium

Small

Not Known

Continuation sort is suitable to sort the elements in range 1 to k

K is Large

K is not known

K may be small or large

K is small

In stable sorting algorithm.

If duplicate elements remain in the same relative position after sorting

One array is used

More than one arrays are required

Duplicating elements not handled

Which may be a stable sort?

Merger

Insertion

Both above

None of the above

An in place sorting algorithm is one that uses ____ arrays for storage

Two dimensional arrays

More than one array

No Additional Array

None of the above

Continuing sort has time complexity of ?

$O(n)$

$O(n+k)$

$O(n \log n)$

$O(k)$

We do sorting to,

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Made by

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In Sieve Technique we donot know which item is of interest

True

False

A (an) _____ is a left-complete binary tree that conforms to the heap order

heap

binary tree

binary search tree

array

27. The sieve technique works in _____ as follows

phases

numbers

integers

routines

For the sieve technique we solve the problem,

recursively

mathematically

precisely

accurately

29. For the heap sort, access to nodes involves simple _____ operations.

arithmetic

binary

algebraic

logarithmic

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

arithmetic

geometric

linear

orthogonal

For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

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Made by

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Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

Select correct option:

n items

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Question # 9 of 10 (Start time: 07:45:36 AM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

For the heap sort we store the tree nodes in

Select correct option:

level-order traversal

in-order traversal

pre-order traversal

post-order traversal

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

upper

lower

average

$\log n$

single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

Made by

Muhammad Usama and DUA sister

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

$(\log n)$ order

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

$T(n)$

$T(n / 2)$

$\log n$

$n / 2 + n / 4$

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

The sieve technique works in _____ as follows

Select correct option:

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numbers

integers

routines

For the Sieve Technique we take time

Select correct option:

$T(nk)$

$T(n / 3)$

n^2

$n/3$

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

linear

arithmetic

geometric

exponent

Made by

Muhammad Usama and DUA sister

Analysis of Selection algorithm ends up with,

Select correct option:

$T(n)$

$T(1 / 1 + n)$

$T(n / 2)$

$T((n / 2) + n)$

Quiz Start Time: 07:23 PM

Time Left 90

sec(s)

Question # 1 of 10 (Start time: 07:24:03 PM) Total M a r k s : 1

In in-place sorting algorithm is one that uses arrays for storage :

Select correct option:

An additional array

No additional array

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

Time Left 89

sec(s)

Question # 2 of 10 (Start time: 07:25:20 PM) Total M a r k s : 1

Which sorting algorithm is faster :

Select correct option:

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

In stable sorting algorithm:

Select correct option:

One array is used

In which duplicating elements are not handled.

More then one arrays are required.

Duplicating elements remain in same relative position after sorting.

Counting sort has time complexity:

Select correct option:

$O(n)$

$O(n+k)$

$O(k)$

$O(n \log n)$

Made by

Muhammad Usama and DUA sister

Counting sort is suitable to sort the elements in range 1 to k:

Select correct option:

K is large

K is small

K may be large or small

None

Memorization is :

Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of recursive calls and looking them again if needed later

To make the process accurate.

None of the above

The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

small

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Made by

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Stable and not in place

Some time in place and send some time stable

For the Sieve Technique we take time

T(nk)

T(n / 3)

n²

n/3

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

Many

1

Few

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decrease and conquer

greedy nature

2-dimension Maxima

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Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of recursive calls and looking them again if needed later

To make the process accurate.

None of the above

Made by

Muhammad Usama and DUA sister

One Example of in place but not stable sort is

Quick

Heap

Merge

Bubble

The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Question # 9 of 10 (Start time: 07:39:07 PM) Total M a r k s : 1

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

Small

CS502 - Fundamentals of Algorithms

Quiz No.2 DEC 03, 2012

Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

Selection sort

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

Made by

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In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

small

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Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

Counting sort has time complexity:

Select correct option:

$O(n)$

$O(n+k)$

$O(k)$

$O(n \log n)$

In which order we can sort?

Select correct option:

increasing order only

decreasing order only

increasing order or decreasing order

both at the same time

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

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The analysis of Selection algorithm shows the total running time is indeed _____ in n ,
Select correct option:

- arithmetic
- geometric
- linear
- orthogonal

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

Select correct option:

There is explicit combine process as well to conquer the solution.

No work is needed to combine the sub-arrays, the array is already sorted

Merging the sub arrays

None of above.

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

- upper
- lower
- average
- $\log n$

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

$T(n)$

$T(n / 2)$

$\log n$

$n / 2 + n / 4$

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The number of nodes in a complete binary tree of height h is

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$$2^{(h+1)} - 1$$

$$2 * (h+1) - 1$$

$$2 * (h+1)$$

$$((h+1) ^ 2) - 1$$

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

$n / 2$ elements

$(n / 2) + n$ elements

$n / 4$ elements

$2 n$ elements

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

We do sorting to,

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Slow sorting algorithms run in,

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

One of the clever aspects of heaps is that they can be stored in arrays without using any

Pointers

Constants

Variables

Functions

Counting sort is suitable to sort the elements in range 1 to k:

K is large

K is small

K may be large or small

None

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Muhammad Usama and DUA sister

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Question # 2 of 10 (Start time: 06:19:38 PM) Total Marks: 1

Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,

Select correct option:

left-complete

right-complete

tree nodes

tree leaves

Question # 3 of 10 (Start time: 06:20:18 PM) Total Marks: 1

Sieve Technique can be applied to selection problem?

Select correct option:

True

False

Question # 4 of 10 (Start time: 06:21:10 PM) Total Marks: 1

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

$(\log n)$ order

Question # 5 of 10 (Start time: 06:21:39 PM) Total Marks: 1

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Question # 6 of 10 (Start time: 06:22:04 PM) Total Marks: 1

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Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

Question # 7 of 10 (Start time: 06:22:40 PM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

Question # 8 of 10 (Start time: 06:23:26 PM) Total Marks: 1

The recurrence relation of Tower of Hanoi is given below $T(n) = \begin{cases} 1 & \text{if } n=1 \\ 2T(n-1) & \text{if } n > 1 \end{cases}$ In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option:

16

10

32

31

Question # 9 of 10 (Start time: 06:24:44 PM) Total Marks: 1

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

Question # 10 of 10 (Start time: 06:25:43 PM) Total Marks: 1

For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

algebraic

logarithmic

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Muhammad Usama and DUA sister

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Slow sorting algorithms run in,

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

$T(n)$

$T(n/2)$

$\log n$

$n/2 + n/4$

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

Made by

Muhammad Usama and DUA sister

1

few

In which order we can sort?

Select correct option:

increasing order only

decreasing order only

increasing order or decreasing order

both at the same time

The recurrence relation of Tower of Hanoi is given below $T(n) = \begin{cases} 1 & \text{if } n=1 \\ 2T(n-1) & \text{if } n > 1 \end{cases}$ In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option:

16

10

32

31

Analysis of Selection algorithm ends up with,

Select correct option:

$T(n)$

$T(1 / 1 + n)$

$T(n / 2)$

$T((n / 2) + n)$

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

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Select correct option:

arithmetic

geometric

linear

orthogonal

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

Select correct option:

$n / 2$ elements

$(n / 2) + n$ elements

$n / 4$ elements

$2n$ elements

Sieve Technique can be applied to selection problem?

Select correct option:

True

false

For the heap sort we store the tree nodes in

Select correct option:

level-order traversal

in-order traversal

pre-order traversal

post-order traversal

One of the clever aspects of heaps is that they can be stored in arrays without using any

_____.

Select correct option:

pointers

constants

variables

functions

Made by

Muhammad Usama and DUA sister

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

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Sieve

smaller sub problems

Selection

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Select correct option:

left-complete

right-complete

tree nodes

tree leaves

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

(log n) order

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in (log n) order

keep elements in increasing or decreasing order

Made by

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How many elements do we eliminate in each time for the Analysis of Selection algorithm?

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How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

Question # 1 of 10 (Start time: 08:17:23 AM) Total M a r k s : 1

The number of nodes in a complete binary tree of height h is

Select correct option:

$2^{(h+1)} - 1$

$2 * (h+1) - 1$

$2 * (h+1)$

$((h+1) ^ 2) - 1$

Question # 2 of 10 (Start time: 08:18:46 AM) Total M a r k s : 1

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Question # 3 of 10 (Start time: 08:19:38 AM) Total M a r k s : 1

In Sieve Technique we do not know which item is of interest

Select correct option:

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True

False

Question # 4 of 10 (Start time: 08:20:33 AM) Total M a r k s: 1

Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,

Select correct option:

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Question # 5 of 10 (Start time: 08:21:59 AM) Total M a r k s: 1

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

$T(n)$

$T(n / 2)$

$\log n$

$n / 2 + n / 4$

Question # 6 of 10 (Start time: 08:23:01 AM) Total M a r k s: 1

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Theta asymptotic notation for $T(n)$:

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Set of functions described by: $c_1g(n)$ Set of functions described by $c_1g(n) \geq f(n)$ for c_1 s

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Question # 8 of 10 (Start time: 08:24:39 AM) Total M a r k s: 1

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

1

few

Question # 9 of 10 (Start time: 08:25:54 AM) Total M a r k s: 1

Sieve Technique applies to problems where we are interested in finding a single item from a

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larger set of _____

Select correct option:

n items

phases

pointers

constant

Question # 10 of 10 (Start time: 08:26:44 AM) Total M a r k s: 1

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numbers

integers

routines

Memorization is?

To store previous results for future use

To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later

To make the process accurate

None of the above

Question # 2 of 10 Total M a r k s: 1

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False

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Question # 9 of 10 (Start time: 07:45:36 AM) Total Marks: 1

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Select correct option:

$T(n)$

Made by

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$T(1 / 1 + n)$

$T(n / 2)$

$T((n / 2) + n)$

Quiz Start Time: 07:23 PM

Time Left 90

sec(s)

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An additional array

No additional array

Both of above may be true according to algorithm

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Time Left 89

sec(s)

Question # 2 of 10 (Start time: 07:25:20 PM) Total M a r k s: 1

Which sorting algorithm is faster :

Select correct option:

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

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Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

small

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Stable and not in place

Some time in place and send some time stable

For the Sieve Technique we take time

$T(nk)$

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$T(n/3)$

n^2

$n/3$

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

Many

1

Few

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Stable and not in place

Some time in place and send some time stable

Memoization is :

Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of recursive calls and looking them again if needed later

To make the process accurate.

None of the above

One Example of in place but not stable sort is

Quick

Heap

Merge

Bubble

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The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Question # 9 of 10 (Start time: 07:39:07 PM) Total M a r k s : 1

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

Small

CS502 - Fundamentals of Algorithms Quiz No.3 Dated 28-01-2013

In in-place sorting algorithm is one that uses arrays for storage :

An additional array

No additional array (Right Answer)

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

The running time of quick sort depends heavily on the selection of

No of inputs

Arrangement of elements in array

Size o elements

Pivot element (Right Answer)

In stable sorting algorithm

One array is used

In which duplicating elements are not handled.

More then one arrays are required.

Duplicating elements remain in same relative position after sorting. (Right Answer)

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$ (Right Answer)

$O(n^3)$

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In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Large

Medium

Not known

Small (Right Answer)

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

There is explicit combine process as well to conquer the solution. (Right Answer)

No work is needed to combine the sub-arrays, the array is already sorted

Merging the subarrays

None of above.

There is relationship between number of back edges and number of cycles in DFS

Select correct option:

Both are equal.

Cycles are half of back edges.

Cycles are one fourth of back edges.

There is no relationship between back edges and number of cycle (Right Answer)

You have an adjacency list for G , what is the time complexity to compute Graph transpose G^T ?

Select correct option:

$(V+E)$ (Right Answer)

$V \cdot E$

V

E

Question # 3 of 10 (Start time: 06:54:27 PM) Total Marks: 1

You have an adjacency list for G , what is the time complexity to compute Graph transpose G^T .?

$(V + E)$ Right Answer)

$(V \cdot E)$

(V)

(V^2)

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

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Select correct option:

log (V) (Right Answer)

V.V

E.E

log (E)

Dijkstra's algorithm :

Select correct option:

Has greedy approach to find all shortest paths

Has both greedy and Dynamic approach to find all shortest paths

Has greedy approach to compute single source shortest paths to all other vertices (Right Answer)

Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

(log E)

? (V)

? (V+E)

(log V) (Right Answer)

Which is true statement in the following.

Kruskal algorithm is multiple source technique for finding MST.

Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is $O(EV)$

Both of above

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges) (Right Answer)

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

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There is no relationship between no. of edges and cycles (Right Answer)

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

True (Right Answer)

False

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$\log(V)$

V.V

E.E

$\log(E)$

Suppose that a graph $G = (V, E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$ (Right Answer)

$O(|V|^2|E|)$

$O(|V| + |E|)$

What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

Select correct option:

Lists require less space than matrices but take longer to find the weight of an edge (v_1, v_2)

Lists require less space than matrices and they are faster to find the weight of an edge (v_1, v_2) (Right Answer)

Lists require more space than matrices and they take longer to find the weight of an edge (v_1, v_2)

Lists require more space than matrices but are faster to find the weight of an edge (v_1, v_2)

What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

A dense undirected graph is:

Select correct option:

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A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

In digraph $G=(V,E)$;G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (Right Answer)

The DFS forest has both back and forward edge

BFS forest has forward edge

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Right Answer)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is a predecessor of u in the tree.

None of above

Using ASCII standard the string "abacdaacacwe" will be encoded with _____ bits

Select correct option:

64

128 (Right Answer)

96

120

Cross edge is :

Select correct option:

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

Which statement is true?

Select correct option:

If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

Both of above (Right Answer)

None of above

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10 If you find yourself in maze the better traversal approach will be

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

Which is true statement.

Select correct option:

Breadth first search is shortest path algorithm that works on un-weighted graphs (Right Answer)

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

None of above are true.

Forward edge is:

Select correct option:

(u, v) where u is a proper descendent of v in the tree.

(u, v) where v is a proper descendent of u in the tree. (Right Answer)

(u, v) where v is a proper ancestor of u in the tree.

(u, v) where u is a proper ancestor of v in the tree.

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Right Answer)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is a predecessor of u in the tree.

None of above

Suppose that a graph $G = (V, E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G?

Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$ (Right Answer)

$O(|V|^2|E|)$

$O(|V| + |E|)$

In digraph $G=(V,E)$;G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (Right Answer)

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The DFS forest has both back and forward edge

BFS forest has forward edge

What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The Isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

If you find yourself in maze the better traversal approach will be :

BFS

BFS and DFS both are valid (Right Answer)

Level order

DFS

Cross edge is :

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few

True (Right Answer)

False

You have an adjacency list for G, what is the time complexity to compute Graph transpose G^T ?

$O(V + E)$ Right Answer)

? $O(V E)$

? $O(V)$

? $O(V^2)$

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v .

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v and vice versa. (Right Answer)

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A digraph is strongly connected if for at least one pair of vertex $u, v \in V$, u can reach v and vice versa.

A digraph is strongly connected if at least one third pair of vertices $u, v \in V$, u can reach v and vice versa.

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (Right Answer)

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

CS502 - Fundamentals of Algorithms Quiz No.4 Dated FEB 05, 2013

In in-place sorting algorithm is one that uses arrays for storage :

An additional array

No additional array (Right Answer)

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

The running time of quick sort depends heavily on the selection of:

No of inputs

Arrangement of elements in array

Size o elements

Pivot element (Right Answer)

In stable sorting algorithm

One array is used

In which duplicating elements are not handled.

More then one arrays are required.

Duplicating elements remain in same relative position after sorting. (Right Answer)

Which sorting algorithm is faster :

$O(n^2)$

Made by

Muhammad Usama and DUA sister

$O(n \log n)$

$O(n+k)$ (Right Answer)

$O(n^3)$

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Large

Medium

Not known

Small (Right Answer)

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

There is explicit combine process as well to conquer the solution. (Right Answer)

No work is needed to combine the sub-arrays, the array is already sorted

Merging the subarrays

None of above.

There is relationship between number of back edges and number of cycles in DFS

Select correct option:

Both are equal.

Cycles are half of back edges.

Cycles are one fourth of back edges.

There is no relationship between back edges and number of cycle (Right Answer)

You have an adjacency list for G , what is the time complexity to compute Graph transpose G^T

Select correct option:

$(V+E)$ (Right Answer)

$V \cdot E$

V

E

Dijkstra's algorithm :

Select correct option:

Has greedy approach to find all shortest paths

Has both greedy and Dynamic approach to find all shortest paths

Has greedy approach to compute single source shortest paths to all other vertices (page 154)

Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

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What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$O(\log E)$

? (V)

? $(V+E)$

$O(\log V)$ (page #152)

Which is true statement in the following.

Kruskal algorithm is multiple source technique for finding MST.

Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is $O(EV)$

Both of above

=>Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

True (Right Answer)

False

What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The Isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

Which statement is true?

Select correct option:

If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

Both of above (Right Answer)

None of above

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

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A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

Which is true statement.

Select correct option:

Breadth first search is shortest path algorithm that works on un-weighted graphs (Right Answer)

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

None of above are true.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (page #142)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v .

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v and vice versa. (Page #135)

A digraph is strongly connected if for at least one pair of vertex $u, v \in V$, u can reach v and vice versa.

A digraph is strongly connected if at least one third pair of vertices $u, v \in V$, u can reach v and vice versa.

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (p131)

Question # 2 of 10 (Start time: 10:35:36 PM) Total Marks: 1

Suppose that a graph $G = (V,E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

Select correct option:

$O(|V|^2)$

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$O(|V| + |E|)$

$O(|V|^2|E|)$

$O(|V| + |E|)$ pg 116

Question # 4 of 10 (Start time: 10:37:30 PM) Total Marks: 1

Forward edge is:

Select correct option:

(u, v) where u is a proper descendent of v in the tree.

(u, v) where v is a proper descendent of u in the tree. Pg 129

(u, v) where v is a proper ancestor of u in the tree.

(u, v) where u is a proper ancestor of v in the tree.

Question # 5 of 10 (Start time: 10:37:58 PM) Total Marks: 1

Using ASCII standard the string "abacdaacacwe" will be encoded with _____ bits

Select correct option:

64

128

96 pg 101 $12 * 8 = 96$

120

Question # 7 of 10 (Start time: 10:38:40 PM) Total Marks: 1

If you find yourself in maze the better traversal approach will be :

Select correct option:

BFS

BFS and DFS both are valid (pg 119)

Level order

DFS

Question # 8

In digraph $G=(V,E)$;G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (pg 131)

The DFS forest has both back and forward edge

BFS forest has forward edge

Question # 9

Made by

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What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

Select correct option:

Lists require less space than matrices but take longer to find the weight of an edge (v1,v2)

Lists require less space than matrices and they are faster to find the weight of an edge (v1, v2)
(pg 116)

Lists require more space than matrices and they take longer to find the weight of an edge (v1, v2)

Lists require more space than matrices but are faster to find the weight of an edge (v1, v2)

Question # 10

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Pg 128)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is a predecessor of u in the tree.

None of above

=====

My 3rd Quiz

<http://cs-mcqs.blogspot.com/2012/06/data-structures-algorithms-multiple.html>

FINALTERM EXAMINATION

Question No: 2

Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

▶ True

▶ False

Question No: 3

If a problem is in NP, it must also be in P.

▶ True

▶ False

▶ unknown

Question No: 5

If a graph has v vertices and e edges then to obtain a spanning tree we have to delete

▶ v edges.

▶ $v - e + 5$ edges

▶ $v + e$ edges.

▶ None of these

Question No: 6

Maximum number of vertices in a Directed Graph may be $|V^2|$

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▶ **True** ▶ False

Question No: 7

The Huffman algorithm finds a (n) _____ solution.

▶ **Optimal** ▶ Non-optimal ▶ Exponential ▶ Polynomial

Question No: 8

The Huffman algorithm finds an exponential solution ▶ True ▶ **False**

Question No: 9

The Huffman algorithm finds a polynomial solution ▶ True ▶ **False**

Question No: 10

The greedy part of the Huffman encoding algorithm is to first find two nodes with **larger** frequency. ▶ True ▶ **False**

Question No: 11

The codeword assigned to characters by the Huffman algorithm have the property that no codeword is the postfix of any other. ▶ True ▶ **False**

Question No: 12

Huffman algorithm uses a greedy approach to generate a postfix code T that minimizes the expected length B (T) of the encoded string. ▶ True ▶ **False**

Question No: 13

Shortest path problems can be solved efficiently by modeling the road map as a graph.

▶ **True** ▶ False

Question No: 14

Dijkstra's single source shortest path algorithm works if all edges weights are non-negative and there are negative cost cycles. ▶ True ▶ **False**

Question No: 15

Bellman-Ford allows negative weights edges and negative cost cycles ▶ True ▶ **False**

Question No: 16

The term "coloring" came from the original application which was in architectural design.

▶ **True** ▶ False

Question No: 17

In the clique cover problem, for two vertices to be in the same group, they must be adjacent to each other. ▶ **True** ▶ False

Question No: 18

Dijkstra's algorithm is operated by maintaining a subset of vertices ▶ **True** ▶ False

Question No: 19

Made by

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The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a different key. ▶ **True** ▶ False

Question No: 21

We do sorting to,

- ▶ keep elements in random positions ▶ keep the algorithm run in linear order
- ▶ keep the algorithm run in $(\log n)$ order
- ▶ **keep elements in increasing or decreasing order**

Question No: 22

After partitioning array in Quick sort, pivot is placed in a position such that

- ▶ **Values smaller than pivot are on left and larger than pivot are on right**
- ▶ Values larger than pivot are on left and smaller than pivot are on right
- ▶ **Pivot is the first element of array** Pivot is the last element of array

Question No: 23

Merge sort is stable sort, but not an in-place algorithm ▶ **True (p#54)** ▶ False

Question No: 24

In counting sort, once we know the ranks, we simply _____ numbers to their final positions in an output array.

- ▶ Delete ▶ **copy (p#57)** ▶ Mark ▶ arrange

Question No: 25

Dynamic programming algorithms need to store the results of intermediate sub-problems. ▶ **True p#75** ▶ False

Question No: 26

A $p \times q$ matrix A can be multiplied with a $q \times r$ matrix B. The result will be a $p \times r$ matrix C. There are $(p \cdot r)$ total entries in C and each takes _____ to compute.

- ▶ **$O(q)$ (p= 84)** ▶ $O(1)$ ▶ $O(n^2)$ ▶ $O(n^3)$

FINAL TERM EXAMINATION

Question No: 2

Which of the following is calculated with **big O notation**?

- Lower bounds Upper bounds
- Both upper and lower bound Medium bounds

Question No: 3

Merge sort makes two recursive calls. Which statement is true after these recursive calls finish, but before the merge step?

- The array elements form a heap
- Elements in each half of the array are sorted amongst themselves
- Elements in the first half of the array are less than or equal to elements in the second half of the array

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None of the above

Question No: 4

Who invented Quick sort procedure?

Hoare Sedgewick Mellroy Coreman

Question No: 6

Consider the following Huffman Tree

The binary code for the string TEA is

10 00 010

011 00 010

10 00 110

11 10 110

Question No: 7

If a graph has v vertices and e edges then to obtain a spanning tree we have to delete v edges.

v $e + 5$ edges $v + e$ edges. None of these

Question No: 8

Can an adjacency matrix for a directed graph ever not be square in shape?

Yes No

Question No: 9

One of the clever aspects of heaps is that they can be stored in arrays without using any

_____ **Pointers (p #40)** constants variables functions

Question No: 10

Merge sort requires extra array storage, **True p #54)** False

Mergesort is a stable algorithm but not an in-place algorithm. It requires extra array storage.

Question No: 11

Non-optimal or greedy algorithm for money change takes _____

O(k) (p#99) O(kN) O(2k) O(N)

Question No: 12

The Huffman codes provide a method of encoding data **inefficiently** when coded using ASCII standard. True **False (p# 99)**

*The Huffman codes provide a method of encoding data **efficiently**.*

Question No: 13

Using ASCII standard the string abacdaacac will be encoded with _____ bits.

80 (p# 99) 160 320 100

Consider the string " abacdaacac". if the string is coded with ASCII codes, the message length would be $10 \times 8 = 80$ bits.

Question No: 14

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Muhammad Usama and DUA sister

Using ASCII standard the string abacdaacac will be encoded with 160 bits.

True **False (p# 99)**

Question No: 15

Using ASCII standard the string abacdaacac will be encoded with 320 bits.

True **False (p# 99)**

Question No: 16

Using ASCII standard the string abacdaacac will be encoded with 100 bits.

True **False (p# 99)**

Question No: 17

Using ASCII standard the string abacdaacac will be encoded with 32 bytes

True **False (p# 99)**

Question No: 18

The greedy part of the Huffman encoding algorithm is to first find two nodes with **smallest** frequency.

True (p# 100) False

Question No: 19

The greedy part of the Huffman encoding algorithm is to first find two nodes with **character** frequency

True **False (p# 100)**

Question No: 20

Huffman algorithm uses a greedy approach to generate an antefix code T that minimizes the expected length $B(T)$ of the encoded string.

True (p# 102) False

Question No: 21

Depth first search is shortest path algorithm that works on un-weighted graphs.

True **False (p# 153)**

*The **breadth-first-search** algorithm we discussed earlier is a shortest-path algorithm that works on un-weighted graphs*

Question No: 22

Dijkstra's single source shortest path algorithm works if all edges weights are nonnegative and there are no negative cost cycles.

True (p# 159) False

Question No: 23

Dijkstra's single source shortest path algorithm works if all edges weights are negative and there are no negative cost cycles.

True (p# 159) False

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Question No: 24

Floyd-Warshall algorithm is a dynamic programming algorithm; the genius of the algorithm is in the clever recursive formulation of the shortest path problem.

True (p# 162) False

Question No: 25

Floyd-Warshall algorithm, as in the case with DP algorithms, we avoid recursive evaluation by generating a table for

k

$ij d$

True

False

the case with DP algorithms, we will avoid recursive evaluation by generating a table for $d(k)ij$

Question No: 26

The term coloring came from the original application which was in map drawing.

True (p# 173) False

Question No: 27

In the clique cover problem, for two vertices to be in the same group, they must be _____ each other.

Apart from Far from Near to **Adjacent to (P# 176)**

Question No: 28

In the clique cover problem, for two vertices to be in the same group, they must be apart from each other.

True **False (P# 176)**

Question No: 29

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a different key.

True (P # 156) not sure False

Question No: 30

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a same key.

True **False (P # 156) not sure**

Quiz no# 4 06-07-2012 solved by umair sid 100%

What algorithm technique is used in the implementation of Kruskal's solution for the MST?

Greedy Technique page #142

in drsigne $G=(V,E)$; G has cycle if and only if

Made by

Muhammad Usama and DUA sister

The DFS forest has back edge page # 131

Question # 9 of 10

Cross edge is :

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another pg 129

(u, v) where u and v are either ancestor or descendent of one another.

Forward edge is :

(u,v) where v is a proper descendent of u in the tree. Page # 129

You have an adjacency list for G, what is the time complexity to compute graph transpose G^T ?

(V + E) PAGE # 138

Given an adjacency list for G, it is possible to compute G^T in $\Theta(V + E)$ time.

It takes $O(\log V)$ to extract a vertex from the priority queue.

There is relationship between number of back edges and number of cycles in DFS

There is no relationship between back edges and number of cycles

Which is true statement:

Breadth first search is shortest path algorithm that works on un-weighted graphs

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

Overall time for Kruskal is

$\Theta(E \log E) = \Theta(E \log V)$ if the graph is sparse. **P-149**

True

Question No: 1

An optimization problem is one in which you want to find,

- ▶ Not a solution
- ▶ An algorithm
- ▶ Good solution
- ▶ **The best solution**

Question No: 2

Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

- ▶ **True**
- ▶ False

Question No: 3

If a problem is in NP, it must also be in P.

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- ▶ **True**
- ▶ False
- ▶ unknown

Question No: 5

If a graph has v vertices and e edges then to obtain a spanning tree we have to delete

- ▶ v edges.
- ▶ $v - e + 5$ edges
- ▶ $v + e$ edges.
- ▶ **None of these**

Question No: 6

Maximum number of vertices in a Directed Graph may be $|V|^2$

- ▶ **True**
- ▶ False

Question No: 7

The Huffman algorithm finds a (n) _____ solution.

- ▶ **Optimal**
- ▶ Non-optimal
- ▶ Exponential
- ▶ Polynomial

Question No: 8

The Huffman algorithm finds an exponential solution ▶ True ▶ **False**

Question No: 9

The Huffman algorithm finds a polynomial solution ▶ **True** ▶ False

Question No: 10

The greedy part of the Huffman encoding algorithm is to first find two nodes with larger frequency. ▶ True ▶ **False**

Question No: 11

The codeword assigned to characters by the Huffman algorithm have the property that no codeword is the postfix of any other. ▶ **True** ▶ False

Question No: 12

Huffman algorithm uses a greedy approach to generate a postfix code T that minimizes the expected length $B(T)$ of the encoded string. ▶ True ▶ **False**

Question No: 13

Shortest path problems can be solved efficiently by modeling the road map as a graph.

- ▶ **True** ▶ False

Question No: 14

Dijkstra's single source shortest path algorithm works if all edges weights are non-negative and there are negative cost cycles. ▶ **True** ▶ False

Question No: 15

Bellman-Ford allows negative weights edges and negative cost cycles.

- ▶ True ▶ **False**

Question No: 16

The term "coloring" came from the original application which was in architectural design. ▶ True ▶ **False**

Question No: 17

In the clique cover problem, for two vertices to be in the same group, they must be adjacent to each other. ▶ **True** ▶ False

Question No: 18

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Dijkstra's algorithm is operates by maintaining a subset of vertices ▶ **True** ▶ False

Question No: 19

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a different key. ▶ **True** ▶ False

Question No: 21

We do sorting to,

- ▶ keep elements in random positions
- ▶ keep the algorithm run in linear order
- ▶ keep the algorithm run in $(\log n)$ order
- ▶ **keep elements in increasing or decreasing order**

▶ Question No: 22

After partitioning array in Quick sort, pivot is placed in a position such that

- ▶ **Values smaller than pivot are on left and larger than pivot are on right**
- ▶ Values larger than pivot are on left and smaller than pivot are on right
- ▶ Pivot is the first element of array
- ▶ Pivot is the last element of array

Question No: 23

Merge sort is stable sort, but not an in-place algorithm ▶ **True** ▶ False

Question No: 24

In counting sort, once we know the ranks, we simply _____ numbers to their final positions in an output array.

- ▶ Delete ▶ **copy** ▶ Mark ▶ arrange

Question No: 25

Dynamic programming algorithms need to store the results of intermediate sub-problems. ▶ **True** ▶ False

Using ASCII standard the string abacdaaac will be encoded with _____ bits.

80 160 320 100

Using ASCII standard the string abacdaaac will be encoded with 160 bits.

True **False**

Using ASCII standard the string abacdaaac will be encoded with 320 bits.

True **False**

Using ASCII standard the string abacdaaac will be encoded with 100 bits.

True **False**

The Huffman algorithm finds a (n) _____ solution.

- ▶ **Optimal** ▶ Non-optimal ▶ Exponential ▶ Polynomial

Huffman algorithm uses a greedy approach to generate a postfix code T that minimizes the expected length $B(T)$ of the encoded string.

- ▶ True
- ▶ **False**

2: Which statement is true?

- If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

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• **If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.**

- both of above
- none of above

5: What general property of the list indicates that the graph has an isolated vertex?

- There is Null pointer at the end of list.
- **The Isolated vertex is not handled in list.**
- Only one value is entered in the list.
- There is at least one null list.

6: Which is true statement.

- Breadth first search is shortest path algorithm that works on un-weighted graphs.
- Depth first search is shortest path algorithm that works on un-weighted graphs.
- **Both of above are true.**
- None of above are true.

11: Using ASCII standard the string “abacdaacacwe” will be encoded with _____ bits

- 64
- 128
- **96**
- 120

13: the analysis of selection algorithm shows the total running time is indeed-----in n.

- arithmetic
- geometric
- **linear**
- orthogonal

14: back edge is

(1) In Prim’s algorithm, the additional information maintained by the algorithm is the length of the shortest edge from vertex v to points already in the tree.

- A) TRUE
- B) FALSE**
- C) UNKNOWN

(2) Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

- A) TRUE.**
- B) FALSE
- C: UNKNOWN

(3) If a problem is NP-complete, it must also be in NP.

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A) TRUE. B) FALSE C) UNKNOWN

(4) Which statement is true

(I) The running time of Bellman-Ford algorithm is $T(V^2E)$

(II) Both Dijkstra's algorithm and Bellman-Ford are based on performing repeated relaxations

(III) The 0-1 knapsack problem is hard to solve

• Only I • Only III • Both I and III • **All of these**

5) Which of the following arrays represent descending (max) heaps?

I. [10,7,7,2,4,6] II. [10,7,6,2,4,7]

III. [10,6,7,2,4,6] IV. [6,6,7,2,4,10]

• **Only II** • Only IV • Both II and IV • Both I and III

6. Which of the following statement(s) is/are correct?

(a) $O(n \log n + n^2) = O(n^2)$. (b) $O(n \log n + n^2) = O(n^2 \log 2n)$

(c) $O(c n^2) = O(n^2)$ where c is a constant. (d) $O(c n^2) = O(c)$ where c is a constant.

(e) $O(c) = O(1)$ where c is a constant.

• **Only (a) & (e)** • Both (c) and (e)

7. Which of the shortest path algorithms would be most appropriate for finding paths in the graph with negative edge weights and cycles?

I. Dijkstra's Algorithm

II. Bellman-Ford Algorithm

III. Floyd Warshall Algorithm

• Only II • Only III • **Both II & III**

9. Suppose we have two problems A and B. Problem A is polynomial-time reducible and problem B is NP-complete. If we reduce problem A into B then problem A becomes NP-complete

• **Yes** • No

11. The recurrence relation of Tower of Hanoi is given below

? 1 if $n = 1$

$T_n = ?$

$-133()$

$2(T_{n-1} + 1)$ if $n > 1$

In order to move a tower of 6 rings from one peg to another, how many moves are required?

• 15 • 7 • 63 • **32**

12. Edge (u, v) is a forward edge if

• u is a proper descendant of v in the tree

• **v is a proper descendant of u in the tree**

• None of these

13. Is $2^{2n} = O(2^n)$?

2^{n-26} ?

14. If, in a DFS forest of digraph $G = (V, E)$, $f[u] = f[v]$ for an edge $(u, v) \in E$ then the edge is called

• **Back edge** • Forward edge • Cross Edge • Tree Edge • None of these

16. Best and worst case times of an algorithm may be same.

• **True** • False

17. Can an adjacency matrix for a directed graph ever not be square in shape?

• **Yes** • No

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1. In which order we can sort?

- increasing order only
- decreasing order only
- **increasing order or decreasing order**
- both at the same time

2. heap is a left-complete binary tree that conforms to the _____

- increasing order only
- decreasing order only
- **heap order**
- (log n) order

3. In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

- $T(n)$
- **$T(n/2)$**
- $\log n$
- $n/2 + n/4$

4. How much time merge sort takes for an array of numbers?

- $T(n^2)$
- $T(n)$
- $T(\log n)$
- **$T(n \log n)$**

5. One of the clever aspects of heaps is that they can be stored in arrays without using any _____.

- **pointers**
- constants
- variables
- functions

6. the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis

- linear
- arithmetic
- **geometric**
- exponent

7. Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

- n items
- phases
- pointers
- constant

8. The sieve technique works in _____ as follows

- **phases**
- numbers
- integers
- routines

9. For the heap sort, access to nodes involves simple _____ operations.

- **arithmetic**
- binary
- algebraic
- logarithmic

10. The analysis of Selection algorithm shows the total running time is indeed _____ in n,

- arithmetic
- geometric
- **linear**
- orthogonal

11. Divide-and-conquer as breaking the problem into a small number of _____

- pivot
- Sieve
- **smaller sub problems**
- Selection

12. Slow sorting algorithms run in,

- **$T(n^2)$**
- $T(n)$
- $T(\log n)$
- $T(n \log n)$

13. A heap is a left-complete binary tree that conforms to the _____

- increasing order only
- decreasing order only
- **heap order**
- (log n) order

14. For the heap sort we store the tree nodes in _____

- **level-order traversal**
- in-order traversal
- pre-order traversal
- post-order traversal

15. The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

- **divide-and-conquer**,
- decrease and conquer
- greedy nature
- 2-dimension Maxima

16. We do sorting to, Select correct option:

- keep elements in random positions
- keep the algorithm run in linear order
- keep the algorithm run in (log n) order
- **keep elements in increasing or decreasing order**

17. Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort, Select correct option:

- upper
- **lower**
- average
- log n

For the heap sort we store the tree nodes in _____ Select correct option:

- **level-order traversal**
- in-order traversal
- pre-order traversal
- post-order traversal

20: In Sieve Technique we do not know which item is of interest Select correct option:

- **True**
- False

21: Slow sorting algorithms run in,

- $T(n^2)$
- $T(n)$
- $T(\log n)$
- **$T(n \log n)$**

22: Divide-and-conquer as breaking the problem into a small number of _____

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- pivot • Sieve • **smaller sub problems** • Selection
- 23: For the sieve technique we solve the problem,
• **recursively** • mathematically • precisely • accurately
- 24: we do sorting to,
• keep elements in random positions • keep the algorithm run in linear order
• keep the algorithm run in $(\log n)$ order • **keep elements in increasing or decreasing order**
- 25: The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,
• **divide-and-conquer** • decrease and conquer • greedy nature • 2-dimension Maxima
- 26: In Sieve Technique we do not know which item is of interest
• **true** • false
- 27: In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,
• $T(n)$ • $T(n/2)$ • **log n** • $n/2 + n/4$
- 28: Divide-and-conquer as breaking the problem into a small number of
• pivot • Sieve • **smaller sub problems** • Selection
- 29: A heap is a left-complete binary tree that conforms to the _____
• increasing order only • decreasing order only • **heap order** • $(\log n)$ order
- 30: Slow sorting algorithms run in,
• $T(n^2)$ • $T(n)$ • $T(\log n)$ • **$T(n \log n)$**
- 31: One of the clever aspects of heaps is that they can be stored in arrays without using any _____.
• **pointers** • constants • variables • functions
- 32: Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort, • upper • **lower** • average • $\log n$
- 33: For the sieve technique we solve the problem,
• mathematically • precisely • accurately • **recursively**
- 34: Sieve Technique can be applied to selection problem?
• **True** • False
- 37: Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,
• **left-complete** • right-complete • tree nodes • tree leaves
- 38: How many elements do we eliminate in each time for the Analysis of Selection algorithm?
• $n/2$ elements • **$(n/2) + n$ elements** • $n/4$ elements • $2n$ elements
- 39: We do sorting to,
• keep elements in random positions • keep the algorithm run in linear order
• keep the algorithm run in $(\log n)$ order • **keep elements in increasing or decreasing order**
- 40: In which order we can sort?
• increasing order only • decreasing order only
• **increasing order or decreasing order** • both at the same time
- 41: : In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as, • $T(n)$ • $T(n/2)$ • **log n** • $n/2 + n/4$
- 42: The sieve technique is a special case, where the number of sub problems is just
• 5 • Many • **1** • few
- Question No: 1 **no need**
- Random access machine or RAM is a/an
- ▶ Machine build by Al-Khwarizmi
 - ▶ Mechanical machine
 - ▶ Electronics machine

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▶ Mathematical model

Question No: 2

_____ is a graphical representation of an algorithm

- ▶ Σ notation
- ▶ Θ notation
- ▶ **Flowchart**
- ▶ Asymptotic notation

Question No: 3

A RAM is an idealized machine with _____ random-access memory.

- ▶ 256MB
- ▶ 512MB
- ▶ **an infinitely large**
- ▶ 100GB

Question No: 4

What type of instructions Random Access Machine (RAM) can execute? Choose best answer

- ▶ Algebraic and logic
- ▶ Geometric and arithmetic
- ▶ **Arithmetic and logic**
- ▶ Parallel and recursive

Question No: 5 -

What will be the total number of max comparisons if we run brute-force maxima algorithm with n elements?

- ▶ **n^2**
- ▶ $2n/n$
- ▶ n
- ▶ $8n$

Question No: 6

What is the solution to the recurrence $T(n) = T(n/2) + n$.

- ▶ $O(\log n)$
- ▶ **$O(n)$**
- ▶ $O(n \log n)$
- ▶ $O(n^2)$

Question No: 7

Consider the following code:

```
For(j=1; j<n;j++)
  For(k=1; k<15;k++)
    For(l=5; l<n; l++)
    {
      Do_something_constant();
    }
```

What is the order of execution for this code.

- ▶ **$O(n)$**
- ▶ $O(n^3)$
- ▶ $O(n^2 \log n)$

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- ▶ $O(n^2)$

Question No: 8

Consider the following Algorithm:

```
Factorial (n){
  if (n=1)
    return 1
  else
    return (n * Factorial(n-1))
}
```

{
Recurrence for the following algorithm is:

- ▶ $T(n) = T(n-1) + 1$
- ▶ $T(n) = nT(n-1) + 1$
- ▶ $T(n) = T(n-1) + n$
- ▶ **$T(n) = T(n(n-1)) + 1$**

Question No: 9 -

What is the total time to heapify?

- ▶ **$O(\log n)$**
- ▶ $O(n \log n)$
- ▶ $O(n^2 \log n)$
- ▶ $O(\log^2 n)$

Question No: 10

When we call heapify then at each level the comparison performed takes time

- ▶ **It will take $\Theta(1)$**
- ▶ Time will vary according to the nature of input data
- ▶ It can not be predicted
- ▶ It will take $\Theta(\log n)$

CS502 - Fundamentals of Algorithms

Quiz No.5 Dated FEB 15TH 2013

In in-place sorting algorithm is one that uses arrays for storage :

An additional array

No additional array (Right Answer)

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

The running time of quick sort depends heavily on the selection of

No of inputs

Arrangement of elements in array

Size o elements

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Pivot element (Right Answer)

In stable sorting algorithm

One array is used

In which duplicating elements are not handled.

More than one arrays are required.

Duplicating elements remain in same relative position after sorting. (Right Answer)

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$ (Right Answer)

$O(n^3)$

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Large

Medium

Not known

Small (Right Answer)

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

There is explicit combine process as well to conquer the solution. (Right Answer)

No work is needed to combine the sub-arrays, the array is already sorted

Merging the subarrays

None of above.

There is relationship between number of back edges and number of cycles in DFS

Select correct option:

Both are equal.

Cycles are half of back edges.

Cycles are one fourth of back edges.

There is no relationship between back edges and number of cycle (Right Answer)

You have an adjacency list for G , what is the time complexity to compute Graph

transpose G^T ?

Select correct option:

$(V+E)$ (Right Answer)

$V \cdot E$

V

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E

Question # 3 of 10 (Start time: 06:54:27 PM) Total Marks: 1

You have an adjacency list for G, what is the time complexity to compute Graph transpose G^T ?

$O(V + E)$ (Right Answer)

$O(V E)$

$O(V)$

$O(V^2)$

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$\log(V)$ (Right Answer)

$V.V$

$E.E$

$\log(E)$

Dijkstra's algorithm :

Select correct option:

Has greedy approach to find all shortest paths

Has both greedy and Dynamic approach to find all shortest paths

Has greedy approach to compute single source shortest paths to all other vertices (Right Answer)

Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$O(\log E)$

$O(V)$

$O(V+E)$

$O(\log V)$ (Right Answer)

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Which is true statement in the following.

Kruskal algorithm is multiple source technique for finding MST.

Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is $O(EV)$

Both of above

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges) (Right Answer)

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (Right Answer)

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

True (Right Answer)

False

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$\log(V)$

V.V

E.E

$\log(E)$

Suppose that a graph $G = (V,E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$ (Right Answer)

$O(|V|^2|E|)$

$O(|V| + |E|)$

What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

Select correct option:

Lists require less space than matrices but take longer to find the weight of an edge (v_1, v_2)

Lists require less space than matrices and they are faster to find the weight of an edge (v_1, v_2) (Right Answer)

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Lists require more space than matrices and they take longer to find the weight of an edge (v_1, v_2)

Lists require more space than matrices but are faster to find the weight of an edge (v_1, v_2)

What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

In digraph $G=(V,E)$;G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (Right Answer)

The DFS forest has both back and forward edge

BFS forest has forward edge

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Right Answer)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is a predecessor of u in the tree.

None of above

Using ASCII standard the string "abacdaacacwe" will be encoded with _____ bits

Select correct option:

64

128 (Right Answer)

96

120

Cross edge is :

Select correct option:

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(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

Which statement is true?

Select correct option:

If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

Both of above (Right Answer)

None of above

10 If you find yourself in maze the better traversal approach will be

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

Which is true statement.

Select correct option:

Breadth first search is shortest path algorithm that works on un-weighted graphs (Right Answer)

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

None of above are true.

Forward edge is:

Select correct option:

(u, v) where u is a proper descendent of v in the tree.

(u, v) where v is a proper descendent of u in the tree. (Right Answer)

(u, v) where v is a proper ancestor of u in the tree.

(u, v) where u is a proper ancestor of v in the tree.

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Right Answer)

(u, v) where u is an ancestor of v in the tree.

(u, v) where v is an predecessor of u in the tree.

None of above

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Suppose that a graph $G = (V, E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$ (Right Answer)

$O(|V|^2|E|)$

$O(|V| + |E|)$

In digraph $G=(V,E)$; G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (Right Answer)

The DFS forest has both back and forward edge

BFS forest has forward edge

What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The Isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

If you find yourself in maze the better traversal approach will be :

BFS

BFS and DFS both are valid (Right Answer)

Level order

DFS

Cross edge is :

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u .

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

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Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few

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True (Right Answer)

False

You have an adjacency list for G , what is the time complexity to compute Graph transpose G^T ?

?(V + E) Right Answer)

? (V E)

? (V)

? (V²)

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v .

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v and vice versa. (Right Answer)

A digraph is strongly connected if for at least one pair of vertex $u, v \in V$, u can reach v and vice versa.

A digraph is strongly connected if at least one third pair of vertices $u, v \in V$, u can reach v and vice versa.

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (Right Answer)

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

In in-place sorting algorithm is one that uses arrays for storage :

An additional array

No additional array (Right Answer)

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

The running time of quick sort depends heavily on the selection of

No of inputs

Arrangement of elements in array

Size o elements

Pivot element (Right Answer)

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In stable sorting algorithm

One array is used

In which duplicating elements are not handled.

More than one array is required.

Duplicating elements remain in same relative position after sorting. (Right Answer)

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$ (Right Answer)

$O(n^3)$

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Large

Medium

Not known

Small (Right Answer)

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

There is explicit combine process as well to conquer the solution. (Right Answer)

No work is needed to combine the sub-arrays, the array is already sorted

Merging the subarrays

None of above.

There is relationship between number of back edges and number of cycles in DFS

Select correct option:

Both are equal.

Cycles are half of back edges.

Cycles are one fourth of back edges.

There is no relationship between back edges and number of cycle (Right Answer)

You have an adjacency list for G , what is the time complexity to compute Graph transpose G^T ?

Select correct option:

$(V+E)$ (Right Answer)

$V \cdot E$

V

E

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Question # 3 of 10 (Start time: 06:54:27 PM) Total Marks: 1

You have an adjacency list for G, what is the time complexity to compute Graph transpose G^T ?

$O(V + E)$ (Right Answer)

$O(V E)$

$O(V)$

$O(V^2)$

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$O(\log V)$ (Right Answer)

$V.V$

$E.E$

$\log(E)$

Dijkstra's algorithm :

Select correct option:

Has greedy approach to find all shortest paths

Has both greedy and Dynamic approach to find all shortest paths

Has greedy approach to compute single source shortest paths to all other vertices (Right Answer)

Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$O(\log E)$

$O(V)$

$O(V+E)$

$O(\log V)$ (Right Answer)

Which is true statement in the following.

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Kruskal algorithm is multiple source technique for finding MST.

Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is $O(EV)$

Both of above

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges) (Right Answer)

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (Right Answer)

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

True (Right Answer)

False

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$\log(V)$

V.V

E.E

$\log(E)$

Suppose that a graph $G = (V, E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$ (Right Answer)

$O(|V|^2|E|)$

$O(|V| + |E|)$

What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

Select correct option:

Lists require less space than matrices but take longer to find the weight of an edge (v_1, v_2)

Lists require less space than matrices and they are faster to find the weight of an edge (v_1, v_2) (Right Answer)

Lists require more space than matrices and they take longer to find the weight of an edge (v_1, v_2)

Lists require more space than matrices but are faster to find the weight of an edge (v_1, v_2)

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What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The Isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

In digraph $G=(V,E)$;G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (Right Answer)

The DFS forest has both back and forward edge

BFS forest has forward edge

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Right Answer)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is an predecessor of u in the tree.

None of above

Using ASCII standard the string "abacdaacacwe" will be encoded with _____ bits

Select correct option:

64

128 (Right Answer)

96

120

Cross edge is :

Select correct option:

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

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Which statement is true?

Select correct option:

If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

Both of above (Right Answer)

None of above

10 If you find yourself in maze the better traversal approach will be

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

Which is true statement.

Select correct option:

Breadth first search is shortest path algorithm that works on un-weighted graphs (Right Answer)

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

None of above are true.

Forward edge is:

Select correct option:

(u, v) where u is a proper descendent of v in the tree.

(u, v) where v is a proper descendent of u in the tree. (Right Answer)

(u, v) where v is a proper ancestor of u in the tree.

(u, v) where u is a proper ancestor of v in the tree.

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Right Answer)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is an predecessor of u in the tree.

None of above

Suppose that a graph $G = (V, E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

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Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$ (Right Answer)

$O(|V|^2|E|)$

$O(|V| + |E|)$

In digraph $G=(V,E)$; G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (Right Answer)

The DFS forest has both back and forward edge

BFS forest has forward edge

What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

If you find yourself in maze the better traversal approach will be :

BFS

BFS and DFS both are valid (Right Answer)

Level order

DFS

Cross edge is :

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u .

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few

True (Right Answer)

False

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You have an adjacency list for G , what is the time complexity to compute Graph transpose G^T ?

?(V + E) (Right Answer)

? (V E)

? (V)

? (V²)

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v .

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v and vice versa. (Right Answer)

A digraph is strongly connected if for at least one pair of vertex $u, v \in V$, u can reach v and vice versa.

A digraph is strongly connected if at least one third pair of vertices $u, v \in V$, u can reach v and vice versa.

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (Right Answer)

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

Selection sort

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

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In Quick sort algorithm, constants hidden in $T(n \lg n)$ are
Select correct option:

Large

Medium

Not known

small

How much time merge sort takes for an array of numbers?
Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

Counting sort has time complexity:
Select correct option:

$O(n)$

$O(n+k)$

$O(k)$

$O(n \log n)$

In which order we can sort?
Select correct option:

increasing order only

decreasing order only

increasing order or decreasing order

both at the same time

A (an) _____ is a left-complete binary tree that conforms to the heap order
Select correct option:

heap

binary tree

binary search tree

array

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The analysis of Selection algorithm shows the total running time is indeed _____ in n,
Select correct option:

- arithmetic
- geometric
- linear**
- orthogonal

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

Select correct option:

There is explicit combine process as well to conquer the solution.

No work is needed to combine the sub-arrays, the array is already sorted

Merging the sub arrays

None of above.

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

- upper
- lower**
- average
- log n

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

$T(n)$

$T(n / 2)$

log n

$n / 2 + n / 4$

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

There is explicit combine process as well to conquer

No work is needed to combine the sub-arrays, the a

Merging the subarrays

None of above

The number of nodes in a complete binary tree of height h is

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$$2^{(h+1)} - 1$$

$$2 * (h+1) - 1$$

$$2 * (h+1)$$

$$((h+1) ^ 2) - 1$$

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

n / 2 elements

(n / 2) + n elements

n / 4 elements

2 n elements

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

We do sorting to,

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Slow sorting algorithms run in,

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

One of the clever aspects of heaps is that they can be stored in arrays without using any

Pointers

Constants

Variables

Functions

Counting sort is suitable to sort the elements in range 1 to k:

K is large

K is small

K may be large or small

None

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We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Question # 2 of 10 (Start time: 06:19:38 PM) Total Marks: 1

Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,

Select correct option:

left-complete

right-complete

tree nodes

tree leaves

Question # 3 of 10 (Start time: 06:20:18 PM) Total Marks: 1

Sieve Technique can be applied to selection problem?

Select correct option:

True

False

Question # 4 of 10 (Start time: 06:21:10 PM) Total Marks: 1

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

$(\log n)$ order

Question # 5 of 10 (Start time: 06:21:39 PM) Total Marks: 1

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Question # 6 of 10 (Start time: 06:22:04 PM) Total Marks: 1

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Divide-and-conquer as breaking the problem into a small number of
Select correct option:

pivot

Sieve

smaller sub problems

Selection

Question # 7 of 10 (Start time: 06:22:40 PM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

Question # 8 of 10 (Start time: 06:23:26 PM) Total Marks: 1

The recurrence relation of Tower of Hanoi is given below $T(n) = \begin{cases} 1 & \text{if } n=1 \\ 2T(n-1) & \text{if } n > 1 \end{cases}$ In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option:

16

10

32

31

Question # 9 of 10 (Start time: 06:24:44 PM) Total Marks: 1

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

Question # 10 of 10 (Start time: 06:25:43 PM) Total Marks: 1

For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

algebraic

logarithmic

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For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Slow sorting algorithms run in,

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

$T(n)$

$T(n/2)$

$\log n$

$n/2 + n/4$

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

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1

few

In which order we can sort?

Select correct option:

increasing order only

decreasing order only

increasing order or decreasing order

both at the same time

The recurrence relation of Tower of Hanoi is given below $T(n) = \begin{cases} 1 & \text{if } n=1 \\ 2T(n-1) & \text{if } n > 1 \end{cases}$ In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option:

16

10

32

31

Analysis of Selection algorithm ends up with,

Select correct option:

$T(n)$

$T(1 / 1 + n)$

$T(n / 2)$

$T((n / 2) + n)$

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

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Select correct option:

arithmetic

geometric

linear

orthogonal

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

Select correct option:

n / 2 elements

(n / 2) + n elements

n / 4 elements

2 n elements

Sieve Technique can be applied to selection problem?

Select correct option:

True

false

For the heap sort we store the tree nodes in

Select correct option:

level-order traversal

in-order traversal

pre-order traversal

post-order traversal

One of the clever aspects of heaps is that they can be stored in arrays without using any

_____.

Select correct option:

pointers

constants

variables

functions

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A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,

Select correct option:

left-complete

right-complete

tree nodes

tree leaves

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

(log n) order

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in (log n) order

keep elements in increasing or decreasing order

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How many elements do we eliminate in each time for the Analysis of Selection algorithm?

Select correct option:

$n / 2$ elements

$(n / 2) + n$ elements

$n / 4$ elements

$2n$ elements

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

Question # 1 of 10 (Start time: 08:17:23 AM) Total M a r k s : 1

The number of nodes in a complete binary tree of height h is

Select correct option:

$2^{(h+1)} - 1$

$2 * (h+1) - 1$

$2 * (h+1)$

$((h+1) ^ 2) - 1$

Question # 2 of 10 (Start time: 08:18:46 AM) Total M a r k s : 1

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Question # 3 of 10 (Start time: 08:19:38 AM) Total M a r k s : 1

In Sieve Technique we do not know which item is of interest

Select correct option:

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True

False

Question # 4 of 10 (Start time: 08:20:33 AM) Total M a r k s: 1

Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,

Select correct option:

left-complete

right-complete

tree nodes

tree leaves

Question # 5 of 10 (Start time: 08:21:59 AM) Total M a r k s: 1

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

$T(n)$

$T(n / 2)$

$\log n$

$n / 2 + n / 4$

Question # 6 of 10 (Start time: 08:23:01 AM) Total M a r k s: 1

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

Theta asymptotic notation for $T(n)$:

Select correct option:

Set of functions described by: $c_1g(n)$ Set of functions described by $c_1g(n) \geq f(n)$ for c_1 s

Theta for $T(n)$ is actually upper and worst case comp

Set of functions described by:

$c_1g(n)$

Question # 8 of 10 (Start time: 08:24:39 AM) Total M a r k s: 1

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

1

few

Question # 9 of 10 (Start time: 08:25:54 AM) Total M a r k s: 1

Sieve Technique applies to problems where we are interested in finding a single item from a

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larger set of _____

Select correct option:

n items

phases

pointers

constant

Question # 10 of 10 (Start time: 08:26:44 AM) Total M a r k s: 1

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Memorization is?

To store previous results for future use

To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later

To make the process accurate

None of the above

Question # 2 of 10 Total M a r k s: 1

Which sorting algorithm is faster

$O(n \log n)$

$O(n^2)$

$O(n+k)$

$O(n^3)$

Quick sort is

Stable & in place

Not stable but in place

Stable but not in place

Some time stable & some times in place

One example of in place but not stable algorithm is

Merger Sort

Quick Sort

Continuation Sort

Bubble Sort

In Quick Sort Constants hidden in $T(n \log n)$ are

Large

Medium

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Small

Not Known

Continuation sort is suitable to sort the elements in range 1 to k

K is Large

K is not known

K may be small or large

K is small

In stable sorting algorithm.

One array is used

More than one arrays are required

Duplicating elements not handled

duplicate elements remain in the same relative position after sorting

Which may be a stable sort?

Merger

Insertion

Both above

None of the above

An in place sorting algorithm is one that uses ___ arrays for storage

Two dimensional arrays

More than one array

No Additional Array

None of the above

Continuing sort has time complexity of ?

O(n)

O(n+k)

O(nlogn)

O(k)

We do sorting to,

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in (log n) order

keep elements in increasing or decreasing order

In Sieve Technique we donot know which item is of interest

True

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False

A (an) _____ is a left-complete binary tree that conforms to the heap order

heap

binary tree

binary search tree

array

27. The sieve technique works in _____ as follows

phases

numbers

integers

routines

For the sieve technique we solve the problem,

recursively

mathematically

precisely

accurately

29. For the heap sort, access to nodes involves simple _____ operations.

arithmetic

binary

algebraic

logarithmic

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

arithmetic

geometric

linear

orthogonal

For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

algebraic

logarithmic

Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

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Select correct option:

n items

phases

pointers

constant

Question # 9 of 10 (Start time: 07:45:36 AM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

For the heap sort we store the tree nodes in

Select correct option:

level-order traversal

in-order traversal

pre-order traversal

post-order traversal

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

upper

lower

average

$\log n$

single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

Made by

Muhammad Usama and DUA sister

increasing order only

decreasing order only

heap order

(log n) order

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

T(n)

T(n / 2)

log n

n / 2 + n / 4

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

For the Sieve Technique we take time

Select correct option:

T(nk)

T(n / 3)

n²

n/3

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

linear

arithmetic

geometric

exponent

Analysis of Selection algorithm ends up with,

Select correct option:

Made by

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T(n)

$T(1 / 1 + n)$

$T(n / 2)$

$T((n / 2) + n)$

Quiz Start Time: 07:23 PM

Time Left 90

sec(s)

Question # 1 of 10 (Start time: 07:24:03 PM) Total M a r k s: 1

In in-place sorting algorithm is one that uses arrays for storage :

Select correct option:

An additional array

No additional array

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

Time Left 89

sec(s)

Question # 2 of 10 (Start time: 07:25:20 PM) Total M a r k s: 1

Which sorting algorithm is faster :

Select correct option:

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

In stable sorting algorithm:

Select correct option:

One array is used

In which duplicating elements are not handled.

More than one arrays are required.

Duplicating elements remain in same relative position after sorting.

Counting sort has time complexity:

Select correct option:

$O(n)$

$O(n+k)$

$O(k)$

$O(n \log n)$

Counting sort is suitable to sort the elements in range 1 to k:

Select correct option:

K is large

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K is small

K may be large or small

None

Memorization is :

Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of recursive calls and looking them again if needed later

To make the process accurate.

None of the above

The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

small

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Stable and not in place

Some time in place and send some time stable

For the Sieve Technique we take time

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T(nk)

$T(n / 3)$

n^2

$n/3$

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

Many

1

Few

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Stable and not in place

Some time in place and send some time stable

Memoization is :

Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of

recursive calls and looking them again if needed later

To make the process accurate.

None of the above

One Example of in place but not stable sort is

Quick

Heap

Merge

Bubble

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The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Question # 9 of 10 (Start time: 07:39:07 PM) Total M a r k s : 1

In Quick sort algorithm,constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

Small

Theta asymptotic notation for $T(n)$:

Select correct option:

Set of functions described by: $c_1g(n) \leq f(n)$ for c_1 some constant and $n \rightarrow \infty$

Set of functions described by $c_1g(n) \geq f(n)$ for c_1 some constant and $n \rightarrow \infty$

Theta for $T(n)$ is actually upper and worst case complexity of the code

Set of functions described by: $c_1g(n) \leq f(n) \leq c_2g(n)$ for c_1 and c_2 some constants and $n \rightarrow \infty$

CS502 - Fundamentals of Algorithms

Quiz No.4 Dated FEB 05, 2013

In in-place sorting algorithm is one that uses arrays for storage :

An additional array

No additional array (Right Answer)

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

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The running time of quick sort depends heavily on the selection of:

No of inputs

Arrangement of elements in array

Size o elements

Pivot element (Right Answer)

In stable sorting algorithm

One array is used

In which duplicating elements are not handled.

More then one arrays are required.

Duplicating elements remain in same relative position after sorting. (Right Answer)

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$ (Right Answer)

$O(n^3)$

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Large

Medium

Not known

Small (Right Answer)

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

There is explicit combine process as well to conquer the solutin. (Right Answer)

No work is needed to combine the sub-arrays, the array is already sorted

Merging the subarrays

None of above.

There is relationship between number of back edges and number of cycles in DFS

Select correct option:

Both are equal.

Cycles are half of back edges.

Cycles are one fourth of back edges.

There is no relationship between back edges and number of cycle (Right Answer)

You have an adjacency list for G , what is the time complexity to compute Graph transpose G^T

Select correct option:

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(V+E) (Right Answer)

V.E

V

E

Dijkstra's algorithm :

Select correct option:

Has greedy approach to find all shortest paths

Has both greedy and Dynamic approach to find all shortest paths

Has greedy approach to compute single source shortest paths to all other vertices (page 154)

Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$O(\log E)$

? (V)

? (V+E)

$O(\log V)$ (page #152)

Which is true statement in the following.

Kruskal algorithm is multiple source technique for finding MST.

Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is $O(EV)$

Both of above

=>Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

True (Right Answer)

False

What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The Isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

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Which statement is true?

Select correct option:

If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

Both of above (Right Answer)

None of above

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

Which is true statement.

Select correct option:

Breadth first search is shortest path algorithm that works on un-weighted graphs (Right Answer)

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

None of above are true.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (page #142)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v .

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v and vice versa. (Page #135)

A digraph is strongly connected if for at least one pair of vertex $u, v \in V$, u can reach v and vice versa.

A digraph is strongly connected if at least one third pair of vertices $u, v \in V$, u can reach v and vice versa.

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The relationship between number of back edges and number of cycles in DFS is,
Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (p131)

Question # 2 of 10 (Start time: 10:35:36 PM) Total Marks: 1

Suppose that a graph $G = (V,E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$

$O(|V|^2|E|)$

$O(|V| + |E|)$ pg 116

Question # 4 of 10 (Start time: 10:37:30 PM) Total Marks: 1

Forward edge is:

Select correct option:

(u, v) where u is a proper descendent of v in the tree.

(u, v) where v is a proper descendent of u in the tree. Pg 129

(u, v) where v is a proper ancestor of u in the tree.

(u, v) where u is a proper ancestor of v in the tree.

Question # 5 of 10 (Start time: 10:37:58 PM) Total Marks: 1

Using ASCII standard the string "abacdaacacwe" will be encoded with _____ bits

Select correct option:

64

128

96 pg 101 $12 \times 8 = 96$

120

Question # 7 of 10 (Start time: 10:38:40 PM) Total Marks: 1

If you find yourself in maze the better traversal approach will be :

Select correct option:

BFS

BFS and DFS both are valid (pg 119)

Level order

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DFS

Question # 8

In digraph $G=(V,E)$;G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (pg 131)

The DFS forest has both back and forward edge

BFS forest has forward edge

Question # 9

What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

Select correct option:

Lists require less space than matrices but take longer to find the weight of an edge (v1,v2)

Lists require less space than matrices and they are faster to find the weight of an edge (v1, v2)
(pg 116)

Lists require more space than matrices and they take longer to find the weight of an edge (v1, v2)

Lists require more space than matrices but are faster to find the weight of an edge (v1, v2)

Question # 10

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Pg 128)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is an predecessor of u in the tree.

None of above

=====

My 3rd Quiz

<http://cs-mcqs.blogspot.com/2012/06/data-structures-algorithms-multiple.html>

FINALTERM EXAMINATION

Question No: 2

Made by

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Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

- ▶ True ▶ False

Question No: 3

If a problem is in NP, it must also be in P.

- ▶ True ▶ False ▶ unknown

Question No: 5

If a graph has v vertices and e edges then to obtain a spanning tree we have to delete

- ▶ v edges. ▶ $v - e + 5$ edges ▶ $v + e$ edges. ▶ None of these

Question No: 6

Maximum number of vertices in a Directed Graph may be $|V^2|$

- ▶ True ▶ False

Question No: 7

The Huffman algorithm finds a (n) _____ solution.

- ▶ Optimal ▶ Non-optimal ▶ Exponential ▶ Polynomial

Question No: 8

The Huffman algorithm finds an exponential solution ▶ True ▶ False

Question No: 9

The Huffman algorithm finds a polynomial solution ▶ True ▶ False

Question No: 10

The greedy part of the Huffman encoding algorithm is to first find two nodes with larger frequency. ▶ True ▶ False

Question No: 11

The codeword assigned to characters by the Huffman algorithm have the property that no codeword is the postfix of any other. ▶ True ▶ False

Question No: 12

Huffman algorithm uses a greedy approach to generate a postfix code T that minimizes the expected length $B(T)$ of the encoded string. ▶ True ▶ False

Question No: 13

Shortest path problems can be solved efficiently by modeling the road map as a graph.

- ▶ True ▶ False

Question No: 14

Dijkstra's single source shortest path algorithm works if all edges weights are non-negative and there are negative cost cycles. ▶ True ▶ False

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Question No: 15

Bellman-Ford allows negative weights edges and negative cost cycles ▶ True ▶ **False**

Question No: 16

The term “coloring” came form the original application which was in architectural design.

▶ True ▶ False

Question No: 17

In the clique cover problem, for two vertices to be in the same group, they must be adjacent to each other. ▶ **True** ▶ False

Question No: 18

Dijkstra’s algorithm is operates by maintaining a subset of vertices ▶ **True** ▶ False

Question No: 19

The difference between Prim’s algorithm and Dijkstra’s algorithm is that Dijkstra’s algorithm uses a different key. ▶ **True** ▶ False

Question No: 21

We do sorting to,

- ▶ keep elements in random positions ▶ keep the algorithm run in linear order
- ▶ keep the algorithm run in $(\log n)$ order
- ▶ **keep elements in increasing or decreasing order**

Question No: 22

After partitioning array in Quick sort, pivot is placed in a position such that

- ▶ **Values smaller than pivot are on left and larger than pivot are on right**
- ▶ Values larger than pivot are on left and smaller than pivot are on right
- ▶ **Pivot is the first element of array** ▶ Pivot is the last element of array

Question No: 23

Merge sort is stable sort, but not an in-place algorithm ▶ **True (p#54)** ▶ False

Question No: 24

In counting sort, once we know the ranks, we simply _____ numbers to their final positions in an output array.

- ▶ Delete ▶ **copy (p#57)** ▶ Mark ▶ arrange

Question No: 25

Dynamic programming algorithms need to store the results of intermediate sub-problems. ▶ **True p#75)** ▶ False

Question No: 26

A $p \times q$ matrix A can be multiplied with a $q \times r$ matrix B. The result will be a $p \times r$ matrix C. There are $(p \cdot r)$ total entries in C and each takes _____ to compute.

- ▶ **$O(q)$ (p= 84)** ▶ $O(1)$ ▶ $O(n^2)$ ▶ $O(n^3)$

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FINAL TERM EXAMINATION

Question No: 2

Which of the following is calculated with **big o notation**?

- Lower bounds **Upper bounds**
Both upper and lower bound Medium bounds

Question No: 3

Merge sort makes two recursive calls. Which statement is true after these recursive calls finish, but before the merge step?

- The array elements form a heap
Elements in each half of the array are sorted amongst themselves
Elements in the first half of the array are less than or equal to elements in the second half of the array
None of the above

Question No: 4

Who invented Quick sort procedure?

- Hoare** Sedgewick Mellroy Coreman

Question No: 6

Consider the following Huffman Tree

The binary code for the string TEA is

- 10 00 010**
011 00 010
10 00 110
11 10 110

Question No: 7

If a graph has v vertices and e edges then to obtain a spanning tree we have to delete v edges.

- v $e + 5$ edges $v + e$ edges. **None of these**

Question No: 8

Can an adjacency matrix for a directed graph ever not be square in shape?

- Yes No

Question No: 9

One of the clever aspects of heaps is that they can be stored in arrays without using any

- _____ **Pointers (p #40)** constants variables functions

Question No: 10

Merge sort requires extra array storage, **True p #54)** False

Mergesort is a stable algorithm but not an in-place algorithm. It requires extra array storage.

Question No: 11

Non-optimal or greedy algorithm for money change takes _____

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O(k) (p#99) O(kN) O(2k) O(N)

Question No: 12

The Huffman codes provide a method of encoding data **inefficiently** when coded using ASCII standard. True **False** (p# 99)

*The Huffman codes provide a method of encoding data **efficiently**.*

Question No: 13

Using ASCII standard the string abacdaacac will be encoded with _____ bits.

80 (p# 99) 160 320 100

*Consider the string " abacdaacac". if the string is coded with ASCII codes, the message length would **be** $10 \times 8 = 80$ bits.*

Question No: 14

Using ASCII standard the string abacdaacac will be encoded with 160 bits.

True **False** (p# 99)

Question No: 15

Using ASCII standard the string abacdaacac will be encoded with 320 bits.

True **False** (p# 99)

Question No: 16

Using ASCII standard the string abacdaacac will be encoded with 100 bits.

True **False** (p# 99)

Question No: 17

Using ASCII standard the string abacdaacac will be encoded with 32 bytes

True **False** (p# 99)

Question No: 18

The greedy part of the Huffman encoding algorithm is to first find two nodes with **smallest** frequency.

True (p# 100) False

Question No: 19

The greedy part of the Huffman encoding algorithm is to first find two nodes with **character** frequency

True **False** (p# 100)

Question No: 20

Huffman algorithm uses a greedy approach to generate an antefix code T that minimizes the expected length B (T) of the encoded string.

False (p# 102)

Question No: 21

Depth first search is shortest path algorithm that works on un-weighted graphs.

True **False** (p# 153)

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The *breadth-first-search* algorithm we discussed earlier is a shortest-path algorithm that works on un-weighted graphs

Question No: 22

Dijkstra's single source shortest path algorithm works if all edges weights are nonnegative and there are no negative cost cycles.

True (p# 159) False

Question No: 23

Dijkstra's single source shortest path algorithm works if all edges weights are negative and there are no negative cost cycles.

False

Question No: 24

Floyd-Warshall algorithm is a dynamic programming algorithm; the genius of the algorithm is in the clever recursive formulation of the shortest path problem.

True (p# 162) False

Question No: 25

Floyd-Warshall algorithm, as in the case with DP algorithms, we avoid recursive evaluation by generating a table for

k

$ij d$

True

False

the case with DP algorithms, we will avoid recursive evaluation by generating a table for $d(k)ij$

Question No: 26

The term coloring came from the original application which was in map drawing.

True (p# 173) False

Question No: 27

In the clique cover problem, for two vertices to be in the same group, they must be _____ each other.

Apart from Far from Near to **Adjacent to (P# 176)**

Question No: 28

In the clique cover problem, for two vertices to be in the same group, they must be apart from each other.

True **False (P# 176)**

Question No: 29

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a different key.

True (P # 156) not sure False

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Question No: 30

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a same key.

True **False (P # 156) not sure**

Quiz no# 4 06-07-2012 solved by umair sid 100%

What algorithm technique is used in the implementation of kruskal solution for the MST?

Greedy Technique page #142

in drsigne $G=(V,E)$;G has cycle if and only if

The DFS forest has back edge page # 131

Question # 9 of 10

Cross edge is :

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another pg 129

(u, v) where u and v are either ancestor or descendent of one another.

Forword edge is :

(u,v) where v ia a proper decendent of u in the tree. Page # 129

You have an adjective list for G, what is the time complexity to computer graph transpose G^T ?

(V + E) PAGE # 138

Given an adjacency list for G, it is possible to compute G^T in $\Theta(V + E)$ time.

It takes $O(\log V)$ to extract a vertex from the priority queue.

There is relationship between number of back edges and number of cycles in DFS

There is no relationship between back edges and number of cycles

Which is true statement:

Breadth first search is shortest path algorithm that works on un-weighted graphs

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

Overall time for Kruskal is

$\Theta(E \log E) = \Theta(E \log V)$ if the graph is sparse. **P-149**

True

Question No: 1

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An optimization problem is one in which you want to find,

- ▶ Not a solution
- ▶ An algorithm
- ▶ Good solution
- ▶ **The best solution**

Question No: 2

Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

- ▶ **True**
- ▶ False

Question No: 3

If a problem is in NP, it must also be in P.

- ▶ **True**
- ▶ False
- ▶ unknown

Question No: 5

If a graph has v vertices and e edges then to obtain a spanning tree we have to delete

- ▶ v edges.
- ▶ $v - e + 5$ edges
- ▶ $v + e$ edges.
- ▶ **None of these**

Question No: 6

Maximum number of vertices in a Directed Graph may be $|V|^2$

- ▶ **True**
- ▶ False

Question No: 7

The Huffman algorithm finds a (n) _____ solution.

- ▶ **Optimal**
- ▶ Non-optimal
- ▶ Exponential
- ▶ Polynomial

Question No: 8

The Huffman algorithm finds an exponential solution ▶ True ▶ **False**

Question No: 9

The Huffman algorithm finds a polynomial solution ▶ **True** ▶ False

Question No: 10

The greedy part of the Huffman encoding algorithm is to first find two nodes with larger frequency. ▶ True ▶ **False**

Question No: 11

The codeword assigned to characters by the Huffman algorithm have the property that no codeword is the postfix of any other. ▶ **True** ▶ False

Question No: 12

Huffman algorithm uses a greedy approach to generate a postfix code T that minimizes the expected length $B(T)$ of the encoded string. ▶ True ▶ **False**

Question No: 13

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Shortest path problems can be solved efficiently by modeling the road map as a graph.

▶ **True** ▶ False

Question No: 14

Dijkstra's single source shortest path algorithm works if all edges weights are non-negative and there are negative cost cycles. ▶ True ▶ **False**

Question No: 15

Bellman-Ford allows negative weights edges and negative cost cycles.

▶ True ▶ **False**

Bellman-Ford allows negative weights edges and no negative cost cycles.

Question No: 16

The term "coloring" came from the original application which was in architectural design. ▶ True ▶ **False**

The term "coloring" comes from the original application which was in map drawing.

Question No: 17

In the clique cover problem, for two vertices to be in the same group, they must be adjacent to each other. ▶ **True** ▶ False

Question No: 18

Dijkstra's algorithm is operates by maintaining a subset of vertices ▶ **True** ▶ False

Question No: 19

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm uses a different key. ▶ **True** ▶ False

Question No: 21

We do sorting to,

- ▶ keep elements in random positions
- ▶ keep the algorithm run in linear order

▶ keep the algorithm run in $(\log n)$ order

▶ **keep elements in increasing or decreasing order**

▶ Question No: 22

After partitioning array in Quick sort, pivot is placed in a position such that

- ▶ **Values smaller than pivot are on left and larger than pivot are on right**
- ▶ Values larger than pivot are on left and smaller than pivot are on right
- ▶ Pivot is the first element of array
- ▶ Pivot is the last element of array

Question No: 23

Merge sort is stable sort, but not an in-place algorithm ▶ **True** ▶ False

Question No: 24

In counting sort, once we know the ranks, we simply _____ numbers to their final positions in an output array.

▶ Delete ▶ **copy** ▶ Mark ▶ arrange

Question No: 25

Dynamic programming algorithms need to store the results of intermediate sub-problems. ▶ **True** ▶ False

Using ASCII standard the string abacdaacac will be encoded with _____ bits.

80 160 320 100

Using ASCII standard the string abacdaacac will be encoded with 160 bits.

True **False**

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Using ASCII standard the string abacdaacac will be encoded with 320 bits.

True **False**

Using ASCII standard the string abacdaacac will be encoded with 100 bits.

True **False**

The Huffman algorithm finds a (n) _____ solution.

▶ **Optimal** ▶ Non-optimal ▶ Exponential ▶ Polynomial

Huffman algorithm uses a greedy approach to generate a postfix code T that minimizes the expected length B (T) of the encoded string.

▶ True

▶ **False**

2: Which statement is true?

- If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.
- **If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.**
- both of above
- none of above

5: What general property of the list indicates that the graph has an isolated vertex?

- There is Null pointer at the end of list.
- **The Isolated vertex is not handled in list.**
- Only one value is entered in the list.
- There is at least one null list.

6: Which is true statement.

- Breadth first search is shortest path algorithm that works on un-weighted graphs.
- Depth first search is shortest path algorithm that works on un-weighted graphs.
- **Both of above are true.**
- None of above are true.

11: Using ASCII standard the string “abacdaacacwe” will be encoded with _____ bits

- 64
- 128
- **96 12*8=96**
- 120

13: the analysis of selection algorithm shows the total running time is indeed-----in n.

- arithmetic

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- geometric
- **linear**
- orthogonal

14: back edge is

(1) In Prim's algorithm, the additional information maintained by the algorithm is the length of the shortest edge from vertex v to points already in the tree.

- A) TRUE
- B) FALSE**
- C) UNKNOWN

(2) Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

- A) TRUE.**
- B) FALSE
- C: UNKNOWN

(3) If a problem is NP-complete, it must also be in NP.

- A) TRUE.**
- B) FALSE
- C) UNKNOWN

(4) Which statement is true

(I) The running time of Bellman-Ford algorithm is $T(V^2)$

(II) Both Dijkstra's algorithm and Bellman-Ford are based on performing repeated relaxations

(III) The 0-1 knapsack problem is hard to solve

- Only I
- Only III
- Both I and III
- **All of these**

5) Which of the following arrays represent descending (max) heaps?

I. [10,7,7,2,4,6]

II. [10,7,6,2,4,7]

III. [10,6,7,2,4,6]

IV. [6,6,7,2,4,10]

- **Only II**
- Only IV
- Both II and IV
- Both I and III

6. Which of the following statement(s) is/are correct?

(a) $O(n \log n + n^2) = O(n^2)$.

(b) $O(n \log n + n^2) = O(n^2 \log 2n)$

(c) $O(c n^2) = O(n^2)$ where c is a constant.

(d) $O(c n^2) = O(c)$ where c is a constant.

(e) $O(c) = O(1)$ where c is a constant.

- **Only (a) & (e)**
- Both (c) and (e)

7. Which of the shortest path algorithms would be most appropriate for finding paths in the graph with negative edge weights and cycles?

I. Dijkstra's Algorithm

II. Bellman-Ford Algorithm

III. Floyd Warshall Algorithm

- Only II
- Only III
- **Both II & III**

9. Suppose we have two problems A and B. Problem A is polynomial-time reducible and problem B is NP-complete. If we reduce problem A into B then problem A becomes NP-complete

- **Yes**
- No

11. The recurrence relation of Tower of Hanoi is given below

? 1 if $n = 1$

$T_n = ?$

-133()

$2(T_{n-1} + 1)$ if $n > 1$

Made by

Muhammad Usama and DUA sister

In order to move a tower of 6 rings from one peg to another, how many moves are required?

- 15
- 7
- 63
- **32**

12. Edge (u, v) is a forward edge if

- u is a proper descendant of v in the tree
- **v is a proper descendant of u in the tree**
- None of these

13. Is $2^{2n} = O(2^n)$?

2^{n-26} ?

14. If, in a DFS forest of digraph $G = (V, E)$, $f[u] = f[v]$ for an edge $(u, v) \in E$ then the edge is called

- **Back edge**
- Forward edge
- Cross Edge
- Tree Edge
- None of these

16. Best and worst case times of an algorithm may be same.

- **True**
- False

17. Can an adjacency matrix for a directed graph ever not be square in shape?

- **Yes**
- No

1. In which order we can sort?

- increasing order only
- decreasing order only
- **increasing order or decreasing order**
- both at the same time

2. heap is a left-complete binary tree that conforms to the _____

- increasing order only
- decreasing order only
- **heap order**
- $(\log n)$ order

3. In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

- $T(n)$
- **$T(n/2)$**
- $\log n$
- $n/2 + n/4$

4. How much time merge sort takes for an array of numbers?

- $T(n^2)$
- $T(n)$
- $T(\log n)$
- **$T(n \log n)$**

5. One of the clever aspects of heaps is that they can be stored in arrays without using any _____.

- **pointers**
- constants
- variables
- functions

6. the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis

- linear
- arithmetic
- **geometric**
- exponent

7. Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

- **n items**
- phases
- pointers
- constant

8. The sieve technique works in _____ as follows

- **phases**
- numbers
- integers
- routines

9. For the heap sort, access to nodes involves simple _____ operations.

- **arithmetic**
- binary
- algebraic
- logarithmic

10. The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

- arithmetic
- geometric
- **linear**
- orthogonal

11. Divide-and-conquer as breaking the problem into a small number of

- pivot
- Sieve
- **smaller sub problems**
- Selection

12. Slow sorting algorithms run in,

- **$T(n^2)$**
- $T(n)$
- $T(\log n)$
- $T(n \log n)$

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14. For the heap sort we store the tree nodes in
- **level-order traversal** • in-order traversal • pre-order traversal • post-order traversal
15. The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,
- **divide-and-conquer**, • decrease and conquer • greedy nature • 2-dimension Maxima
16. We do sorting to, Select correct option:
- keep elements in random positions • keep the algorithm run in linear order
 - keep the algorithm run in $(\log n)$ order • **keep elements in increasing or decreasing order**
17. Sorting is one of the few problems where provable _____ bonds exists on how fast we can sort, Select correct option:
- upper • **lower** • average • $\log n$
- For the heap sort we store the tree nodes in Select correct option:
- **level-order traversal** • in-order traversal • pre-order traversal • post-order traversal
- 20: In Sieve Technique we do not know which item is of interest Select correct option:
- **True** • False
- 21: Slow sorting algorithms run in,
- $T(n^2)$ • $T(n)$ • $T(\log n)$ • **$T(n \log n)$**
- 22: Divide-and-conquer as breaking the problem into a small number of
- pivot • Sieve • **smaller sub problems** • Selection
- 23: For the sieve technique we solve the problem,
- **recursively** • mathematically • precisely • accurately
- 24: we do sorting to,
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- **true** • false
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- $T(n)$ • $T(n/2)$ • **$\log n$** • $n/2 + n/4$
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- **$T(n^2)$** • $T(n)$ • $T(\log n)$
- 31: One of the clever aspects of heaps is that they can be stored in arrays without using any _____.
- **pointers** • constants • variables • functions
- 32: Sorting is one of the few problems where provable _____ bonds exists on how fast we can sort, • upper • **lower** • average • $\log n$
- 33: For the sieve technique we solve the problem,
- mathematically • precisely • accurately • **recursively**
- 34: Sieve Technique can be applied to selection problem?
- **True** • False
- 37: Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,
- **left-complete** • right-complete • tree nodes • tree leaves

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38: How many elements do we eliminate in each time for the Analysis of Selection algorithm?

- $n / 2$ elements
- **$(n / 2) + n$ elements**
- $n / 4$ elements
- $2n$ elements

39: We do sorting to,

- keep elements in random positions
- keep the algorithm run in linear order
- keep the algorithm run in $(\log n)$ order
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- $T(n / 2)$
- **$\log n$**
- $n / 2 + n / 4$

42: The sieve technique is a special case, where the number of sub problems is just

- 5
- Many
- **1**
- few

Question No: 1 **no** **need**

Random access machine or RAM is a/an

- ▶ Machine build by Al-Khwarizmi
- ▶ Mechanical machine
- ▶ Electronics machine
- ▶ **Mathematical model**

Question No: 2

_____ is a graphical representation of an algorithm

- ▶ Σ notation
- ▶ Θ notation
- ▶ **Flowchart**
- ▶ Asymptotic notation

Question No: 3

A RAM is an idealized machine with _____ random-access memory.

- ▶ 256MB
- ▶ 512MB
- ▶ **an infinitely large**
- ▶ 100GB

Question No: 4

What type of instructions Random Access Machine (RAM) can execute? Choose best answer

- ▶ Algebraic and logic
- ▶ Geometric and arithmetic
- ▶ **Arithmetic and logic**
- ▶ Parallel and recursive

Question No: 5 -

What will be the total number of max comparisons if we run brute-force maxima algorithm with n elements?

- ▶ **n^2**
- ▶ $2n/n$
- ▶ n
- ▶ $8n$

Question No: 6

What is the solution to the recurrence $T(n) = T(n/2) + n$.

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- ▶ $O(\log n)$
- ▶ **$O(n)$**
- ▶ $O(n \log n)$
- ▶ $O(n^2)$

Question No: 7

Consider the following code:

```
For(j=1; j<n;j++)
  For(k=1; k<15;k++)
    For(l=5; l<n; l++)
    {
      Do_something_constant();
    }
```

What is the order of execution for this code.

- ▶ **$O(n)$**
- ▶ $O(n^3)$
- ▶ $O(n^2 \log n)$
- ▶ $O(n^2)$

Question No: 8

Consider the following Algorithm:

```
Factorial (n){
  if (n=1)
    return 1
  else
    return (n * Factorial(n-1))
}
```

Recurrence for the following algorithm is:

- ▶ $T(n) = T(n-1) + 1$
- ▶ $T(n) = nT(n-1) + 1$
- ▶ $T(n) = T(n-1) + n$
- ▶ **$T(n) = T(n(n-1)) + 1$**

Question No: 9 -

What is the total time to heapify?

- ▶ **$O(\log n)$**
- ▶ $O(n \log n)$
- ▶ $O(n^2 \log n)$
- ▶ $O(\log^2 n)$

Question No: 10

When we call heapify then at each level the comparison performed takes time

- ▶ **It will take $\Theta(1)$**
- ▶ Time will vary according to the nature of input data
- ▶ It can not be predicted
- ▶ It will take $\Theta(\log n)$

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CS502 - Fundamentals of Algorithms

Quiz No.5 Dated FEB 15TH 2013

In in-place sorting algorithm is one that uses arrays for storage :

An additional array

No additional array (Right Answer)

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

The running time of quick sort depends heavily on the selection of

No of inputs

Arrangement of elements in array

Size o elements

Pivot element (Right Answer)

In stable sorting algorithm

One array is used

In which duplicating elements are not handled.

More then one arrays are required.

Duplicating elements remain in same relative position after sorting. (Right Answer)

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$ (Right Answer)

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In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

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Medium

Not known

Small (Right Answer)

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There is explicit combine process as well to conquer the solutin. (Right Answer)

No work is needed to combine the sub-arrays, the array is already sorted

Merging the subarrays

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None of above.

There is relationship between number of back edges and number of cycles in DFS

Select correct option:

Both are equal.

Cycles are half of back edges.

Cycles are one fourth of back edges.

There is no relationship between back edges and number of cycle (Right Answer)

You have an adjacency list for G, what is the time complexity to compute Graph transpose G^T ?

Select correct option:

$(V+E)$ (Right Answer)

V.E

V

E

Question # 3 of 10 (Start time: 06:54:27 PM) Total Marks: 1

You have an adjacency list for G, what is the time complexity to compute Graph transpose G^T .?

$?(V + E)$ Right Answer)

$?(V E)$

$?(V)$

$?(V^2)$

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$\log (V)$ (Right Answer)

V.V

E.E

$\log (E)$

Dijkstra's algorithm :

Select correct option:

Has greedy approach to find all shortest paths

Has both greedy and Dynamic approach to find all shortest paths

Has greedy approach to compute single source shortest paths to all other vertices (Right Answer)

Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

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What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$O(\log E)$

$? (V)$

$? (V+E)$

$O(\log V)$ (Right Answer)

Which is true statement in the following.

Kruskal algorithm is multiple source technique for finding MST.

Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is $O(EV)$

Both of above

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best Tree edge) when the graph has relatively few edges) (Right Answer)

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (Right Answer)

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

True (Right Answer)

False

What is the time complexity to extract a vertex from the priority queue in Prim's algorithm?

Select correct option:

$\log(V)$

$V.V$

$E.E$

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$\log(E)$

Suppose that a graph $G = (V, E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$ (Right Answer)

$O(|V|^2|E|)$

$O(|V| + |E|)$

What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

Select correct option:

Lists require less space than matrices but take longer to find the weight of an edge (v_1, v_2)

Lists require less space than matrices and they are faster to find the weight of an edge (v_1, v_2) (Right Answer)

Lists require more space than matrices and they take longer to find the weight of an edge (v_1, v_2)

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What general property of the list indicates that the graph has an isolated vertex?

Select correct option:

There is Null pointer at the end of list.

The isolated vertex is not handled in list. (not Sure)

Only one value is entered in the list.

There is at least one null list.

A dense undirected graph is:

Select correct option:

A graph in which $E = O(V^2)$ (Right Answer)

A graph in which $E = O(V)$

A graph in which $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

In digraph $G=(V,E)$; G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

The DFS forest has back edge (Right Answer)

The DFS forest has both back and forward edge

BFS forest has forward edge

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Muhammad Usama and DUA sister

Back edge is:

Select correct option:

(u, v) where v is an ancestor of u in the tree. (Right Answer)

(u,v) where u is an ancestor of v in the tree.

(u, v) where v is a predecessor of u in the tree.

None of above

Using ASCII standard the string "abacdaacacwe" will be encoded with _____ bits

Select correct option:

64

128 (Right Answer)

96

120

Cross edge is :

Select correct option:

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

Which statement is true?

Select correct option:

If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

Both of above (Right Answer)

None of above

10 If you find yourself in maze the better traversal approach will be

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Which is true statement.

Select correct option:

Breadth first search is shortest path algorithm that works on un-weighted graphs (Right Answer)

Depth first search is shortest path algorithm that works on un-weighted graphs.

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Both of above are true.

None of above are true.

Forward edge is:

Select correct option:

(u, v) where u is a proper descendent of v in the tree.

(u, v) where v is a proper descendent of u in the tree. (Right Answer)

(u, v) where v is a proper ancesstor of u in the tree.

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None of above

Suppose that a graph $G = (V,E)$ is implemented using adjacency lists. What is the complexity of a breadth-first traversal of G ?

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BFS

BFS and DFS both are valid (Right Answer)

Level order

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Dynamic Programming Technique

The algorithm combines more than one of the above techniques

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True (Right Answer)

False

You have an adjacency list for G, what is the time complexity to compute Graph transpose G^T ?

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$O(V E)$

$O(V)$

$O(V^2)$

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v .

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v and vice versa. (Right Answer)

A digraph is strongly connected if for at least one pair of vertex $u, v \in V$, u can reach v and vice versa.

A digraph is strongly connected if at least one third pair of vertices $u, v \in V$, u can reach v and vice versa.

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Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

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Question # 3 of 10 (Start time: 06:54:27 PM) Total Marks: 1

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DFS

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Muhammad Usama and DUA sister

Cross edge is :

(u, v) where u and v are not ancestor of one another

(u, v) where u is ancestor of v and v is not descendent of u.

(u, v) where u and v are not ancestor or descendent of one another (Right Answer)

(u, v) where u and v are either ancestor or descendent of one another.

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few

True (Right Answer)

False

You have an adjacency list for G, what is the time complexity to compute Graph transpose G^T ?

$O(V + E)$ (Right Answer)

$O(V E)$

$O(V)$

$O(V^2)$

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v .

A digraph is strongly connected if for every pair of vertices $u, v \in V$, u can reach v and vice versa. (Right Answer)

A digraph is strongly connected if for at least one pair of vertex $u, v \in V$, u can reach v and vice versa.

A digraph is strongly connected if at least one third pair of vertices $u, v \in V$, u can reach v and vice versa.

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

There is no relationship between no. of edges and cycles (Right Answer)

What algorithm technique is used in the implementation of Kruskal solution for the MST?

Greedy Technique (Right Answer)

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

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Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

Selection sort

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

geometric

exponent

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

small

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

Counting sort has time complexity:

Select correct option:

$O(n)$

$O(n+k)$

$O(k)$

$O(n \log n)$

In which order we can sort?

Select correct option:

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increasing order only

decreasing order only

increasing order or decreasing order

both at the same time

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

Select correct option:

arithmetic

geometric

linear

orthogonal

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

Select correct option:

There is explicit combine process as well to conquer the solution.

No work is needed to combine the sub-arrays, the array is already sorted

Merging the sub arrays

None of above.

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

upper

lower

average

log n

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In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

$T(n)$

$T(n/2)$

$\log n$

$n/2 + n/4$

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

There is explicit combine process as well to conquer

No work is needed to combine the sub-arrays, the a

Merging the subarrays

None of above

The number of nodes in a complete binary tree of height h is

$2^{(h+1)} - 1$

$2 * (h+1) - 1$

$2 * (h+1)$

$((h+1)^2) - 1$

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

$n/2$ elements

$(n/2) + n$ elements

$n/4$ elements

$2n$ elements

Which sorting algorithm is faster :

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

We do sorting to,

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Slow sorting algorithms run in,

$T(n^2)$

$T(n)$

$T(\log n)$

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$T(n \log n)$

One of the clever aspects of heaps is that they can be stored in arrays without using any

Pointers

Constants

Variables

Functions

Counting sort is suitable to sort the elements in range 1 to k:

K is large

K is small

K may be large or small

None

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Question # 2 of 10 (Start time: 06:19:38 PM) Total Marks: 1

Heaps can be stored in arrays without using any pointers; this is due to the _____ nature of the binary tree,

Select correct option:

left-complete

right-complete

tree nodes

tree leaves

Question # 3 of 10 (Start time: 06:20:18 PM) Total Marks: 1

Sieve Technique can be applied to selection problem?

Select correct option:

True

False

Question # 4 of 10 (Start time: 06:21:10 PM) Total Marks: 1

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

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increasing order only

decreasing order only

heap order

(log n) order

Question # 5 of 10 (Start time: 06:21:39 PM) Total Marks: 1

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Question # 6 of 10 (Start time: 06:22:04 PM) Total Marks: 1

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

Question # 7 of 10 (Start time: 06:22:40 PM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

Question # 8 of 10 (Start time: 06:23:26 PM) Total Marks: 1

The recurrence relation of Tower of Hanoi is given below $T(n) = \begin{cases} 1 & \text{if } n=1 \\ 2T(n-1) & \text{if } n > 1 \end{cases}$ In

order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option:

16

10

32

31

Question # 9 of 10 (Start time: 06:24:44 PM) Total Marks: 1

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

Made by

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linear

arithmetic

geometric

exponent

Question # 10 of 10 (Start time: 06:25:43 PM) Total Marks: 1

For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

algebraic

logarithmic

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Slow sorting algorithms run in,

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

Select correct option:

linear

arithmetic

Made by

Muhammad Usama and DUA sister

geometric

exponent

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

$T(n)$

$T(n / 2)$

$\log n$

$n / 2 + n / 4$

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

1

few

In which order we can sort?

Select correct option:

increasing order only

decreasing order only

increasing order or decreasing order

both at the same time

The recurrence relation of Tower of Hanoi is given below $T(n) = \{1 \text{ if } n=1 \text{ and } 2T(n-1) \text{ if } n > 1$ In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option:

16

10

32

31

Analysis of Selection algorithm ends up with,

Select correct option:

$T(n)$

$T(1 / 1 + n)$

$T(n / 2)$

$T((n / 2) + n)$

We do sorting to,

Select correct option:

Made by

Muhammad Usama and DUA sister

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

The analysis of Selection algorithm shows the total running time is indeed _____ in n ,

Select correct option:

arithmetic

geometric

linear

orthogonal

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

Select correct option:

$n / 2$ elements

$(n / 2) + n$ elements

$n / 4$ elements

$2n$ elements

Sieve Technique can be applied to selection problem?

Select correct option:

True

false

For the heap sort we store the tree nodes in

Select correct option:

Made by

Muhammad Usama and DUA sister

level-order traversal

in-order traversal
pre-order traversal
post-order traversal

One of the clever aspects of heaps is that they can be stored in arrays without using any

_____.
Select correct option:

pointers

constants
variables
functions

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree
binary search tree
array

Divide-and-conquer as breaking the problem into a small number of

Select correct option:

pivot

Sieve

smaller sub problems

Selection

Heaps can be stored in arrays without using any pointers; this is due to the _____
nature of the binary tree,

Select correct option:

left-complete

right-complete
tree nodes
tree leaves

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically
precisely
accurately

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A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

$(\log n)$ order

We do sorting to,

Select correct option:

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

How many elements do we eliminate in each time for the Analysis of Selection algorithm?

Select correct option:

$n / 2$ elements

$(n / 2) + n$ elements

$n / 4$ elements

$2n$ elements

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

Question # 1 of 10 (Start time: 08:17:23 AM) Total M a r k s : 1

The number of nodes in a complete binary tree of height h is

Select correct option:

$2^{(h+1)} - 1$

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$$2 * (h+1) - 1$$

$$2 * (h+1)$$

$$((h+1) ^ 2) - 1$$

Question # 2 of 10 (Start time: 08:18:46 AM) Total M a r k s : 1

A (an) _____ is a left-complete binary tree that conforms to the heap order

Select correct option:

heap

binary tree

binary search tree

array

Question # 3 of 10 (Start time: 08:19:38 AM) Total M a r k s : 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

Question # 4 of 10 (Start time: 08:20:33 AM) Total M a r k s : 1

Heaps can be stored in arrays without using any pointers; this is due to the

_____ nature of the binary tree,

Select correct option:

left-complete

right-complete

tree nodes

tree leaves

Question # 5 of 10 (Start time: 08:21:59 AM) Total M a r k s : 1

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

T(n)

T(n / 2)

log n

n / 2 + n / 4

Question # 6 of 10 (Start time: 08:23:01 AM) Total M a r k s : 1

For the sieve technique we solve the problem,

Select correct option:

recursively

mathematically

precisely

accurately

Theta asymptotic notation for T (n) :

Select correct option:

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Set of functions described by: $c_1g(n) \geq f(n)$ for $c_1 \leq \theta$

Theta for $T(n)$ is actually upper and worst case comp

Set of functions described by:

$c_1g(n)$

Question # 8 of 10 (Start time: 08:24:39 AM) Total M a r k s: 1

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

many

1

few

Question # 9 of 10 (Start time: 08:25:54 AM) Total M a r k s: 1

Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

Question # 10 of 10 (Start time: 08:26:44 AM) Total M a r k s: 1

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

Memorization is?

To store previous results for future use

To avoid this unnecessary repetitions by writing down the results of recursive calls and looking them up again if we need them later

To make the process accurate

None of the above

Question # 2 of 10 Total M a r k s: 1

Which sorting algorithm is faster

$O(n \log n)$

$O(n^2)$

$O(n+k)$

$O(n^3)$

Quick sort is

Made by

Muhammad Usama and DUA sister

Stable & in place

Not stable but in place

Stable but not in place

Some time stable & some times in place

One example of in place but not stable algorithm is

Merger Sort

Quick Sort

Continuation Sort

Bubble Sort

In Quick Sort Constants hidden in $T(n \log n)$ are

Large

Medium

Small

Not Known

Continuation sort is suitable to sort the elements in range 1 to k

K is Large

K is not known

K may be small or large

K is small

In stable sorting algorithm.

One array is used

More than one arrays are required

Duplicating elements not handled

duplicate elements remain in the same relative position after sorting

Which may be a stable sort?

Merger

Insertion

Both above

None of the above

An in place sorting algorithm is one that uses ___ arrays for storage

Two dimensional arrays

More than one array

No Additional Array

None of the above

Continuing sort has time complexity of ?

$O(n)$

Made by

Muhammad Usama and DUA sister

$O(n+k)$

$O(n \log n)$

$O(k)$

We do sorting to,

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in $(\log n)$ order

keep elements in increasing or decreasing order

In Sieve Technique we don't know which item is of interest

True

False

A (an) _____ is a left-complete binary tree that conforms to the heap order

heap

binary tree

binary search tree

array

27. The sieve technique works in _____ as follows

phases

numbers

integers

routines

For the sieve technique we solve the problem,

recursively

mathematically

precisely

accurately

29. For the heap sort, access to nodes involves simple _____ operations.

arithmetic

binary

algebraic

logarithmic

The analysis of Selection algorithm shows the total running time is

indeed _____ in n ,

arithmetic

Made by

Muhammad Usama and DUA sister

geometric

linear

orthogonal

For the heap sort, access to nodes involves simple _____ operations.

Select correct option:

arithmetic

binary

algebraic

logarithmic

Sieve Technique applies to problems where we are interested in finding a single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

Question # 9 of 10 (Start time: 07:45:36 AM) Total Marks: 1

In Sieve Technique we do not know which item is of interest

Select correct option:

True

False

How much time merge sort takes for an array of numbers?

Select correct option:

$T(n^2)$

$T(n)$

$T(\log n)$

$T(n \log n)$

For the heap sort we store the tree nodes in

Select correct option:

level-order traversal

in-order traversal

pre-order traversal

post-order traversal

Sorting is one of the few problems where provable _____ bounds exists on how fast we can sort,

Select correct option:

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upper

lower

average

log n

single item from a larger set of _____

Select correct option:

n items

phases

pointers

constant

A heap is a left-complete binary tree that conforms to the _____

Select correct option:

increasing order only

decreasing order only

heap order

(log n) order

In the analysis of Selection algorithm, we make a number of passes, in fact it could be as many as,

Select correct option:

T(n)

T(n / 2)

log n

$n / 2 + n / 4$

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

The sieve technique works in _____ as follows

Select correct option:

phases

numbers

integers

routines

For the Sieve Technique we take time

Select correct option:

T(nk)

Made by

Muhammad Usama and DUA sister

$T(n/3)$

n^2

$n/3$

In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the convergent _____ series in the analysis,

linear

arithmetic

geometric

exponent

Analysis of Selection algorithm ends up with,

Select correct option:

$T(n)$

$T(1/1+n)$

$T(n/2)$

$T((n/2)+n)$

Quiz Start Time: 07:23 PM

Time Left 90

sec(s)

Question # 1 of 10 (Start time: 07:24:03 PM) Total M a r k s : 1

In in-place sorting algorithm is one that uses arrays for storage :

Select correct option:

An additional array

No additional array

Both of above may be true according to algorithm

More than 3 arrays of one dimension.

Time Left 89

sec(s)

Question # 2 of 10 (Start time: 07:25:20 PM) Total M a r k s : 1

Which sorting algorithm is faster :

Select correct option:

$O(n^2)$

$O(n \log n)$

$O(n+k)$

$O(n^3)$

In stable sorting algorithm:

Select correct option:

One array is used

In which duplicating elements are not handled.

Made by

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More than one arrays are required.

Duplicating elements remain in same relative position after sorting.

Counting sort has time complexity:

Select correct option:

$O(n)$

$O(n+k)$

$O(k)$

$O(n \log n)$

Counting sort is suitable to sort the elements in range 1 to k:

Select correct option:

K is large

K is small

K may be large or small

None

Memorization is :

Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of recursive calls and looking them again if needed later

To make the process accurate.

None of the above

The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size of elements

Pivot elements

Which may be stable sort:

Select correct option:

Bubble sort

Insertion sort

Both of above

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Made by

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Large

Medium

Not known

small

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Stable and not in place

Some time in place and send some time stable

For the Sieve Technique we take time

$T(nk)$

$T(n / 3)$

n^2

$n/3$

The sieve technique is a special case, where the number of sub problems is just

Select correct option:

5

Many

1

Few

The reason for introducing Sieve Technique algorithm is that it illustrates a very important special case of,

Select correct option:

divide-and-conquer

decrease and conquer

greedy nature

2-dimension Maxima

Quick sort is

Select correct option:

Stable and In place

Not stable but in place

Stable and not in place

Some time in place and send some time stable

Made by

Muhammad Usama and DUA sister

Memoization is :

Select correct option:

To store previous results for further use.

To avoid unnecessary repetitions by writing down the results of

recursive calls and looking them again if needed later

To make the process accurate.

None of the above

One Example of in place but not stable sort is

Quick

Heap

Merge

Bubble

The running time of quick sort depends heavily on the selection of

Select correct option:

No of inputs

Arrangement of elements in array

Size o elements

Pivot elements

Question # 9 of 10 (Start time: 07:39:07 PM) Total M a r k s : 1

In Quick sort algorithm, constants hidden in $T(n \lg n)$ are

Select correct option:

Large

Medium

Not known

Small

Theta asymptotic notation for $T(n)$:

Select correct option:

Set of functions described by: $c_1g(n) \leq f(n)$ for c_1 some constant and $n \geq n_0$

Set of functions described by $c_1g(n) \geq f(n)$ for c_1 some constant and $n \geq n_0$

Theta for $T(n)$ is actually upper and worst case complexity of the code

Set of functions described by: $c_1g(n) \leq f(n) \leq c_2g(n)$ for c_1 and c_2 some constants and $n \geq n_0$